ASYMPTOTIC STABILITY OF SHOCK PROFILES AND RAREFACTION WAVES UNDER PERIODIC PERTURBATIONS FOR 1-D CONVEX SCALAR VISCOUS CONSERVATION LAWS

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ABSTRACT. This paper studies the asymptotic stability of shock profiles and rarefaction waves under space-periodic perturbations for one-dimensional convex scalar viscous conservation laws. For the shock profile, we show that the solution approaches the background shock profile with a constant shift in the $L^{\infty}(\mathbb{R})$ norm at exponential rates. The new phenomena contrasting to the case of localized perturbations is that the constant shift cannot be determined by the initial excessive mass in general, which indicates that the periodic oscillations at infinities make contributions to this shift. And the vanishing viscosity limit for the shift is also shown. The key elements of the poof consist of the construction of an ansatz which tends to two periodic solutions as $x \to \pm \infty$, respectively, and the anti-derivative variable argument, and an elaborate use of the maximum principle. For the rarefaction wave, we also show the stability in the $L^{\infty}(\mathbb{R})$ norm.

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1. Introduction and main results

We consider the Cauchy problem for one-dimensional convex scalar viscous conservation laws

$$\partial_t u^{\nu} + \partial_x f(u^{\nu}) = \nu \partial_x^2 u^{\nu}, \qquad x \in \mathbb{R}, \ t > 0, \tag{1.1}$$

$$u^{\nu}(x,0) = u_0(x), \qquad x \in \mathbb{R},\tag{1.2}$$

where $u^{\nu}(x,t) \in \mathbb{R}$ is the unknown, the flux f is smooth and strictly convex, and $\nu \in (0,1]$ denotes the viscosity. This paper is concerned with the asymptotic behavior of the solution $u^{\nu}(x,t)$ to (1.1), (1.2) with $u_0(x) \in L^{\infty}(\mathbb{R})$ satisfying

$$\begin{cases} |u_0(x) - \overline{u}_l - w_{0l}(x)| \leq C_0 e^{\beta_0 x}, \\ |u_0(x) - \overline{u}_r - w_{0r}(x)| \leq C_0 e^{-\beta_0 x}, \end{cases} \quad x \in \mathbb{R},$$

$$(1.3)$$

where $\overline{u}_l, \overline{u}_r, C_0 > 0$ and $\beta_0 > 0$ are constants, and $w_{0l}, w_{0r} \in L^{\infty}(\mathbb{R})$ are two arbitrary periodic functions.

It is well known from [28, 20] that for $\nu > 0$, the equation (1.1) generates a semi-group $\{S_t^{\nu}: L^{\infty}(\mathbb{R}) \to L^{\infty}(\mathbb{R}); t \geq 0\}$ to ensure that, for any initial data $u_0 \in L^{\infty}(\mathbb{R})$, the function $u^{\nu}(x,t) := S_t^{\nu}u_0$ is the unique bounded solution to (1.1), (1.2), which is smooth for t > 0, and satisfies the initial condition in the weak sense: for any continuous function $\varphi(x,t)$ compactly supported in $\mathbb{R} \times [0,+\infty)$, there holds

$$\int_{\mathbb{R}} \left(\varphi(x,t) u^{\nu}(x,t) - \varphi(x,0) u_0(x) \right) dx \to 0 \quad \text{as } t \to 0 + .$$

The semi-group S_t^{ν} satisfies the following classical Co-properties:

- (Comparison) If $u_0, v_0 \in L^{\infty}(\mathbb{R})$ and $u_0 \leq v_0$ almost everywhere, then $S_t^{\nu}u_0 \leq S_t^{\nu}v_0$ for any $x \in \mathbb{R}$, t > 0.
- (Contraction) If $u_0, v_0 \in L^{\infty}(\mathbb{R})$ and $u_0 v_0 \in L^1(\mathbb{R})$, then $S_t^{\nu} u_0 S_t^{\nu} v_0 \in L^1(\mathbb{R})$ and $\|S_t^{\nu} u_0 S_t^{\nu} v_0\|_{L^1(\mathbb{R})}$ is non-increasing with respect to time t.
- (Conservation) If $u_0, v_0 \in L^{\infty}(\mathbb{R})$ and $u_0 v_0 \in L^1(\mathbb{R})$, then

$$\int_{\mathbb{R}} (S_t^{\nu} u_0 - S_t^{\nu} v_0) \, dx = \int_{\mathbb{R}} (u_0 - v_0) dx \qquad \forall \ t \geqslant 0.$$

Moreover, there exists a constant E > 0, depending only on f and $||u_0||_{L^{\infty}}$, such that

$$\partial_x u^{\nu}(x,t) \leqslant \frac{E}{t} \qquad \forall x \in \mathbb{R}, \ t > 0.$$
 (1.4)

Shocks and rarefaction waves are most important nonlinear solutions to conservation laws. A viscous shock profile $\phi^{\nu}(x-st)$ is a classical traveling wave solution to the viscous conservation law (1.1), solving the problem

$$\begin{cases}
\nu(\phi^{\nu})'' = f'(\phi^{\nu})(\phi^{\nu})' - s(\phi^{\nu})', \\
\lim_{x \to -\infty} \phi^{\nu}(x) = \overline{u}_l, & \lim_{x \to +\infty} \phi^{\nu}(x) = \overline{u}_r,
\end{cases}$$
(1.5)

where $\overline{u}_l > \overline{u}_r$ and s is the shock speed defined by the Rankine-Hugoniot condition

$$s = \frac{f(\overline{u}_l) - f(\overline{u}_r)}{\overline{u}_l - \overline{u}_r}.$$

The existence of the shock profile follows from a simple phase plane analysis, and can also follow from the center-manifold theorem in Kopell-Howard [18]. For $\overline{u}_l < \overline{u}_r$, a

centered rarefaction wave

$$u^{R}(x,t) = \begin{cases} \overline{u}_{l}, & \frac{x}{t} < f'(\overline{u}_{l}), \\ (f')^{-1}(\frac{x}{t}), & f'(\overline{u}_{l}) \leq \frac{x}{t} \leq f'(\overline{u}_{r}), \\ \overline{u}_{r}, & \frac{x}{t} > f'(\overline{u}_{r}), \end{cases}$$

is an entropy weak solution to the Riemann problem for the inviscid conservation law (1.1) with $\nu = 0$.

When the initial data u_0 approaches constant states as $|x| \to +\infty$, i.e. $w_{0l} = w_{0r} = 0$ in (1.3), the asymptotic behaviors of solutions to (1.1), (1.2) have been studied widely so far. The pioneering work of Hopf [14] showed the L^{∞} stability of constants with a decay rate $1/\sqrt{t}$, by using an explicit representation of the solution to the Burgers' equation. Later, Il'in-Oleĭnik [16] applied the maximum principle on the anti-derivative variables to prove the L^{∞} stability of constants, shocks and rarefaction waves for general convex conservation laws. Moreover, Freistühler-Serre [5] combined a lap number argument and maximum principle to prove the L^1 stability of viscous shock profiles. For more results, we refer to [27, 11, 15] for the one-dimensional scalar case, [9, 32, 12, 13, 17] for the multi-dimensional scalar case, and [26, 8, 23, 24, 31, 25, 29] for the important one-dimensional system case.

For the initial data which keeps oscillating at infinities, Lax [22] was the first one to study the periodic data. He showed that the periodic entropy solutions to inviscid scalar conservation laws approach their constant averages in the L^{∞} norm at algebraic rates. And then Glimm-Lax [7] and Dafermos [1] used the generalized characteristics to extend the results to some important 2×2 systems. Besides the constants, Xin-Yuan-Yuan [33] and Yuan-Yuan [34] proved the L^{∞} stability of shocks and rarefaction waves under periodic perturbations for the scalar inviscid conservation laws, by using the generalized characteristics. We also refer to [3, 4] for the L^1 stability of the stationary viscous "shock profile" which connects two periodic functions as end states, where the flux in the equation (1.1) is f(x, u) that is periodic with respect to the spatial variable x.

In this paper, we deal with the initial data (1.3), where w_{0l} and w_{0r} are arbitrary periodic functions, in order to see how the initial oscillations at infinities influence the stability of these two nonlinear waves in the viscous case. Throughout this paper, we let $\phi(x)$ denote any fixed shock profile solving (1.5) with $\nu = 1$, and for any $\nu > 0$, we define

$$\phi^{\nu}(x) := \phi\left(\frac{x}{\nu}\right). \tag{1.6}$$

Then ϕ^{ν} solves (1.5) for any $\nu > 0$ and tends to the inviscid Lax-shock

$$u^{S}(x,t) = \begin{cases} \overline{u}_{l}, & x < st, \\ \overline{u}_{r}, & x > st, \end{cases}$$

almost everywhere as the viscosity $\nu \to 0 + .$ With the constants $\overline{u}_l, \overline{u}_r$ and periodic perturbations $w_{0l}, w_{0r} \in L^{\infty}(\mathbb{R})$ in (1.3), we let u_l^{ν}, u_r^{ν} denote the periodic solutions to (1.1) with the respective initial data

$$u_l^{\nu}(x,0) = \overline{u}_l + w_{0l}(x), \quad u_r^{\nu}(x,0) = \overline{u}_r + w_{0r}(x).$$
 (1.7)

Now the main results of this paper are stated as follows:

Theorem 1.1. Assume that $\nu > 0$ and the initial data $u_0 \in L^{\infty}(\mathbb{R})$ satisfies (1.3) with $\overline{u}_l > \overline{u}_r$ and the periodic functions $w_{0l}, w_{0r} \in L^{\infty}$ with the respective periods $p_l, p_r > 0$, satisfying

$$\frac{1}{p_l} \int_0^{p_l} w_{0l}(x) dx = \frac{1}{p_r} \int_0^{p_r} w_{0r}(x) dx = 0.$$
 (1.8)

Then there exist time-independent constants C > 0 and $\mu > 0$ (both of which depend on viscosity ν) such that the unique bounded solution u^{ν} to (1.1), (1.2) satisfies

$$\sup_{x \in \mathbb{R}} |u^{\nu}(x,t) - \phi^{\nu}(x - st - X_{\infty}^{\nu})| \le Ce^{-\mu t}, \quad t > 0, \tag{1.9}$$

with the constant shift $X_{\infty}^{\nu} = \frac{1}{\overline{u}_l - \overline{u}_r} \left(X_{\infty,1}^{\nu} + X_{\infty,2}^{\nu} \right)$ given by

$$X_{\infty,1}^{\nu} = \int_{-\infty}^{0} (u_0 - \phi^{\nu} - w_{0l})(x)dx + \int_{0}^{+\infty} (u_0 - \phi^{\nu} - w_{0r})(x)dx, \tag{1.10}$$

$$X_{\infty,2}^{\nu} = \int_{0}^{+\infty} \frac{1}{p_{l}} \int_{0}^{p_{l}} \left[f(u_{l}^{\nu}(x,t)) - f(\overline{u}_{l}) \right] dx dt - \frac{1}{p_{l}} \int_{0}^{p_{l}} \int_{0}^{x} w_{0l}(y) dy dx$$

$$- \int_{0}^{+\infty} \frac{1}{p_{r}} \int_{0}^{p_{r}} \left[f(u_{r}^{\nu}(x,t)) - f(\overline{u}_{r}) \right] dx dt + \frac{1}{p_{r}} \int_{0}^{p_{r}} \int_{0}^{x} w_{0r}(y) dy dx.$$

$$(1.11)$$

Remark 1.2. In this paper, except Theorem 1.4 or the proof in Section 3.5, our estimates depend heavily on the viscosity coefficient $\nu > 0$.

Theorem 1.1 shows that in contrast to the case of localized perturbations, besides the localized part of the initial perturbation, the periodic oscillations at infinities generate another shift $X_{\infty,2}^{\nu}$ to the background viscous shock profile. The next theorem shows that this shift is non-zero in general even in the case the periods of the perturbations at $x = \pm \infty$ are the same.

Theorem 1.3. Under the assumptions of Theorem 1.1, even if $w_{0l} = w_{0r}$, the constant $X_{\infty,2}^{\nu}$ defined in (1.11) may be non-zero in general. More precisely,

- (1) for the Burgers' equation, i.e. $f(u) = u^2/2$, it holds that $X_{\infty,2}^{\nu} = 0$;
- (2) if w_{0l} (= w_{0r}) satisfies

$$0 < \|w_{0l}\|_{L^{\infty}(\mathbb{R})} < (\overline{u}_l - \overline{u}_r)/2,$$

then there exists a smooth and strictly convex flux f such that $X_{\infty,2}^{\nu} \neq 0$.

However, for the inviscid conservation law (1.1) with $\nu = 0$, it is shown in [33] that if $w_{0l} = w_{0r}$, the entropy solution u^0 tends to the background shock u^S with no shift, i.e. $X_{\infty,2}^0 = 0$ in the inviscid case. The vanishing viscosity limit for the shift $X_{\infty,2}^{\nu}$ is presented in the next theorem, which agrees with the results in [33, 34].

Theorem 1.4. Under the assumptions of Theorem 1.1, as the viscosity $\nu \to 0+$,

$$X_{\infty,2}^{\nu} \to X_{\infty,2}^{0} := -\min_{x \in \mathbb{R}} \int_{0}^{x} w_{0l}(y) dy + \min_{x \in \mathbb{R}} \int_{0}^{x} w_{0r}(y) dy. \tag{1.12}$$

Furthermore, if both w_{0l} and w_{0r} have bounded total variations on their respective periodic domains, there exists a constant C > 0, independent of ν , such that

$$\left| X_{\infty,2}^{\nu} - X_{\infty,2}^{0} \right| \leqslant C \nu^{1/5}. \tag{1.13}$$

At last, we state the result for rarefaction waves.

Theorem 1.5. Assume that $\nu > 0$ and the initial data u_0 satisfies (1.3) with $\overline{u}_l < \overline{u}_r$ and the periodic functions $w_{0l}, w_{0r} \in L^{\infty}$ with the respective periods $p_l, p_r > 0$, satisfying (1.8). Then the unique bounded solution u^{ν} to (1.1), (1.2) satisfies

$$\sup_{x \in \mathbb{R}} \left| u^{\nu}(x,t) - u^{R}(x,t) \right| \to 0 \quad \text{ as } t \to +\infty.$$

Consequently, different from the localized perturbations, i.e., the background shock can absorb all localized perturbations on the two sides and finally tends to itself with no shift (if the perturbation has zero mass), the periodic perturbations at infinities produce infinite perturbations onto the background shock, ended up with a constant shift, which cannot be determined explicitly by the initial perturbations in the viscous case (see (1.11) and (1.12)).

The main difficulty to prove Theorem 1.1 is that the perturbation $u^{\nu} - \phi^{\nu}$ is not integrable anymore, which makes it difficult to use an anti-derivative argument as before that plays an important role in the previous study of the stability under localized perturbations. In fact, if one considers the equation of the perturbation, the coefficient of the zero-order term is $f''(\phi^{\nu})(\phi^{\nu})' < 0$, which makes it harder to use either the maximum principle or the energy method. One of the key elements of our proof is that we find an ansatz $\psi^{\nu}_{X^{\nu}(t)}(x,t)$, where $X^{\nu}(t)$ is a shift function (see (2.15)) such that the difference $u^{\nu} - \psi^{\nu}_{X^{\nu}(t)}$ is integrable and has zero mass for large time. Therefore, it is plausible to study the equation of the anti-derivative variable of the difference $u^{\nu} - \psi^{\nu}_{X^{\nu}(t)}$ (for the Burgers' equation, the ansatz actually coincides with the solution u^{ν} at an arithmetic sequence of time $\{t_k\}$; see Proposition 2.8). We show that the limit of $X^{\nu}(t)-st$ as $t\to +\infty$ is actually the constant shift X^{ν}_{∞} in Theorem 1.1. And although the ansatz $\psi_{X^{\nu}(t)}^{\nu}$ is not a solution to (1.1), the error (see (2.10)) decays exponentially both in space and in time. Then following the idea of Il'in-Oleĭnik [16], one can construct auxiliary functions and use the maximum principle to obtain our main results.

2. Preliminaries and ansatz

We first present some useful lemmas and introduce some notations, and then construct the ansatz. Important properties of the ansatz will be stated as propositions, which will be proved in the rest of the paper. In the end of this section, we outline the organizations of the proof.

Lemma 2.1. Assume that $u_0(x) \in L^{\infty}(\mathbb{R})$ is periodic with period p > 0 and average $\overline{u} = \frac{1}{p} \int_0^p u_0(x) dx$. Then there exists a constant $\alpha > 0$, depending only on p and ν , such that for any integers $k, l \ge 0$, the periodic solution $u^{\nu}(x, t)$ to (1.1), (1.2) satisfies that

$$\left\| \partial_t^k \partial_x^l (u^{\nu} - \overline{u}) \right\|_{L^{\infty}(\mathbb{R})} \leqslant C e^{-\alpha t}, \quad t \geqslant 1, \tag{2.1}$$

where C > 0 is independent of time t.

Lemma 2.1 can be proved by standard energy estimates and the Poincaré inequality, which is given in the Appendix A. Thus, one can choose $\alpha > 0$, depending on p_l, p_r and ν , such that u_l^{ν} and u_r^{ν} defined in (1.7) satisfy (2.1) with $\overline{u} = \overline{u}_l$ and \overline{u}_r , respectively.

Lemma 2.2. Assume that $u_0, \tilde{u}_0 \in L^{\infty}(\mathbb{R})$ and there exist constants C > 0 and $\delta \in \mathbb{R}$ such that

$$|u_0(x) - \tilde{u}_0(x)| \le Ce^{\delta x}, \quad x \in \mathbb{R}.$$

Then it holds that

$$|S_t^{\nu}u_0 - S_t^{\nu}\tilde{u}_0| \leqslant C(t)e^{\delta x}, \quad x \in \mathbb{R}, \ t > 0,$$

where the constant C(t) > 0 is bounded on any compact subset of $[0, +\infty)$.

The proof of Lemma 2.2, based on approximate solutions solving linear parabolic equations, is given in the Appendix B.

For the periodic solutions u_l^{ν} and u_r^{ν} defined in (1.7), the following result can follow from Lemma 2.2.

Lemma 2.3. Assume that the initial data $u_0 \in L^{\infty}(\mathbb{R})$ satisfies (1.3). Then the unique solution u^{ν} to (1.1), (1.2) satisfies that

$$\begin{cases} |u^{\nu}(x,t) - u_l^{\nu}(x,t)| \leq C(t)e^{\beta_0 x}, \\ |u^{\nu}(x,t) - u_r^{\nu}(x,t)| \leq C(t)e^{-\beta_0 x}, \end{cases} \quad x \in \mathbb{R}, t > 0,$$
 (2.2)

where C(t) is bounded on any compact subset of $[0, +\infty)$.

To prove Theorem 1.1, we now construct the ansatz. For the shock profile ϕ^{ν} defined in (1.6), we first define the function

$$g^{\nu}(x) := \frac{\phi^{\nu}(x) - \overline{u}_r}{\overline{u}_l - \overline{u}_r}, \quad x \in \mathbb{R}.$$
 (2.3)

Lemma 2.4. The function $q^{\nu} \in C^{\infty}(\mathbb{R})$ satisfies that

(i) there exist positive constants β_1 and β_2 , depending on ν, f, \overline{u}_l and \overline{u}_r , such that

$$\beta_1 \leqslant \frac{-(g^{\nu})'(x)}{(\overline{u}_l - \overline{u}_r)g^{\nu}(x)(1 - g^{\nu}(x))} \leqslant \beta_2, \qquad x \in \mathbb{R};$$
(2.4)

(ii) with the inequality (2.4), there exists a constant C > 0, depending on ν, f, \overline{u}_l and \overline{u}_r , such that

$$\frac{1}{C}e^{-\beta_{2}x} \leq g^{\nu}(x) \leq Ce^{-\beta_{1}x}, \qquad x > 0,
\frac{1}{C}e^{\beta_{2}x} \leq 1 - g^{\nu}(x) \leq Ce^{\beta_{1}x}, \qquad x < 0,
\frac{1}{C}e^{-\beta_{2}|x|} \leq -(g^{\nu})'(x) \leq Ce^{-\beta_{1}|x|}, \qquad x \in \mathbb{R}.$$
(2.5)

The proof of Lemma 2.4 can be found in [10]. And we will give a simplified proof for the scalar viscous conservation laws in the Appendix C. For convenience, in the following part of this paper we define

$$\beta := \min\{\beta_0, \beta_1, \beta_2\} > 0. \tag{2.6}$$

For any C^1 curve $\xi(t):[0,+\infty)\to\mathbb{R}$, we set

$$g_{\xi}^{\nu}(x) := g^{\nu}(x - \xi(t)), \quad x \in \mathbb{R}, t \geqslant 0,$$
 (2.7)

with the derivatives:

$$(g_{\varepsilon}^{\nu})^{(k)}(x) := (g^{\nu})^{(k)}(x - \xi(t)), \quad k \geqslant 1.$$

Motivated by Lemma 2.3 and the formula of the viscous shock profile

$$\phi_{\xi}^{\nu}(x) := \phi^{\nu}\left(x - \xi(t)\right) = \overline{u}_{l}g_{\xi}^{\nu}(x) + \overline{u}_{r}\left(1 - g_{\xi}^{\nu}(x)\right),\,$$

we construct the ansatz as

$$\psi_{\xi}^{\nu}(x,t) := u_{l}^{\nu}(x,t)g_{\xi}^{\nu}(x) + u_{r}^{\nu}(x,t)\left(1 - g_{\xi}^{\nu}(x)\right). \tag{2.8}$$

It is noted that the shift $\xi(t)$ appears only in g^{ν} . Thus ψ^{ν}_{ξ} satisfies

$$\partial_t \psi_{\varepsilon}^{\nu} + \partial_x f(\psi_{\varepsilon}^{\nu}) - \nu \partial_x^2 \psi_{\varepsilon}^{\nu} = h_{\varepsilon}^{\nu}, \tag{2.9}$$

where the source term h_{ε}^{ν} is

$$h_{\xi}^{\nu} = \partial_{x} f(\psi_{\xi}^{\nu}) - \partial_{x} f(u_{l}^{\nu}) g_{\xi}^{\nu} - \partial_{x} f(u_{r}^{\nu}) (1 - g_{\xi}^{\nu}) - 2\nu \partial_{x} (u_{l}^{\nu} - u_{r}^{\nu}) (g_{\xi}^{\nu})' - (u_{l}^{\nu} - u_{r}^{\nu}) \left((g_{\xi}^{\nu})' \xi' + \nu (g_{\xi}^{\nu})'' \right),$$
(2.10)

which can be rewritten as

$$h_{\xi}^{\nu} = \partial_{x} \left[\left(f(\psi_{\xi}^{\nu}) - f(u_{l}^{\nu}) \right) g_{\xi}^{\nu} + \left(f(\psi_{\xi}^{\nu}) - f(u_{r}^{\nu}) \right) (1 - g_{\xi}^{\nu}) - 2\nu (u_{l}^{\nu} - u_{r}^{\nu}) (g_{\xi}^{\nu})' \right] + \left(f(u_{l}^{\nu}) - f(u_{r}^{\nu}) \right) (g_{\xi}^{\nu})' - (u_{l}^{\nu} - u_{r}^{\nu}) (g_{\xi}^{\nu})' \xi' + \nu (u_{l}^{\nu} - u_{r}^{\nu}) (g_{\xi}^{\nu})''.$$

$$(2.11)$$

This, together with the fact, $\nu(g_{\varepsilon}^{\nu})'' = f'(\phi_{\varepsilon}^{\nu})(g_{\varepsilon}^{\nu})' - s(g_{\varepsilon}^{\nu})'$, yields that

$$h_{\xi}^{\nu} = \left(f'(\psi_{\xi}^{\nu}) - f'(u_{l}^{\nu}) \right) \partial_{x} u_{l}^{\nu} g_{\xi}^{\nu} + \left(f'(\psi_{\xi}^{\nu}) - f'(u_{r}^{\nu}) \right) \partial_{x} u_{r}^{\nu} (1 - g_{\xi}^{\nu}) - 2\nu \partial_{x} (u_{l}^{\nu} - u_{r}^{\nu}) (g_{\xi}^{\nu})' - (u_{l}^{\nu} - u_{r}^{\nu}) \left(\xi'(t) - s + f'(\phi_{\xi}^{\nu}) - f'(\psi_{\xi}^{\nu}) \right) (g_{\xi}^{\nu})'.$$
(2.12)

The formulas (2.11) and (2.12) will be used later.

The ansatz ψ_{ξ}^{ν} is expected to satisfy $\int_{\mathbb{R}} (u^{\nu} - \psi_{\xi}^{\nu})(x,t)dx \equiv 0$, so that the antiderivative variable can vanish at both infinities $x \to \pm \infty$. Under the assumptions of Theorem 1.1, it follows from Lemma 2.1 that there exists a large $T_0 > 1$ such that

$$0 < \frac{\overline{u}_l - \overline{u}_r}{2} < (u_l^{\nu} - u_r^{\nu})(x, t) < 2(\overline{u}_l - \overline{u}_r), \quad x \in \mathbb{R}, t \geqslant T_0.$$
 (2.13)

The time T_0 is chosen to guarantee $\int_{\mathbb{R}} (u_l^{\nu} - u_r^{\nu})(x,t)(g_{\xi}^{\nu})'dx < 0$ for all $t \ge T_0$. It is noted that the terms appearing in the square brackets of (2.11) vanish as $|x| \to \infty$. For the equation of the perturbation,

$$\partial_t (u^{\nu} - \psi_{\xi}^{\nu}) + \partial_x \left(f(u^{\nu}) - f(\psi_{\xi}^{\nu}) \right) = \nu \partial_x^2 (u^{\nu} - \psi_{\xi}^{\nu}) - h_{\xi}^{\nu}, \tag{2.14}$$

we aim to choose a curve $\xi = X^{\nu}(t)$ such that $\int_{\mathbb{R}} h_{X^{\nu}}^{\nu}(x,t) dx = 0$. Integrating (2.11) with respect to x, we require that the curve $X^{\nu}(t)$ solves the problem

$$\begin{cases} (X^{\nu})'(t) = F^{\nu}(X^{\nu}(t), t), & t > T_0, \\ X^{\nu}(T_0) = X_0^{\nu}, \end{cases}$$
 (2.15)

where

$$F^{\nu}(\xi,t) := \frac{\int_{\mathbb{R}} \left[\nu (u_l^{\nu} - u_r^{\nu}) (g_{\xi}^{\nu})'' + (f(u_l^{\nu}) - f(u_r^{\nu})) (g_{\xi}^{\nu})' \right] dx}{\int_{\mathbb{R}} (u_l^{\nu} - u_r^{\nu}) (g_{\xi}^{\nu})' dx}, \tag{2.16}$$

and the initial data $X^{\nu}(T_0) = X_0^{\nu}$ is chosen so that

$$\int_{\mathbb{R}} (u^{\nu} - \psi_{X_0^{\nu}}^{\nu})(x, T_0) dx = 0.$$
 (2.17)

Proposition 2.5. Under the assumptions of Theorem 1.1, there exists a unique $X_0^{\nu} \in \mathbb{R}$ such that (2.17) holds, and the problem (2.15) admits a unique C^{∞} solution $X^{\nu}(t)$ satisfying

$$|X^{\nu}(t) - st - X_{\infty}^{\nu}| \leqslant Ce^{-\alpha t}, \quad t \geqslant T_0, \tag{2.18}$$

where X_{∞}^{ν} is the constant defined in Theorem 1.1 and the constant C > 0 is independent of time t.

Remark 2.6. The choice of $X^{\nu}(t)$ can make the source term $h_{X^{\nu}}^{\nu}(x,t)$ and its anti-derivative variable $\int_{-\infty}^{x} h_{X^{\nu}}^{\nu}(y,t)dy$ decay exponentially fast both in space and in time (see Proposition 3.5 for details), which plays an important role in the proof of Theorem 1.1.

With the shift curve $X^{\nu}(t)$ so determined, we have the following results.

Proposition 2.7. Under the assumptions of Theorem 1.1, there exist time-independent constants C > 0 and $0 < \mu \le \alpha$ (both of which depend on viscosity ν) such that the unique bounded solution u^{ν} to (1.1), (1.2) satisfies

$$\sup_{x \in \mathbb{R}} |u^{\nu}(x,t) - \psi^{\nu}_{X^{\nu}(t)}(x,t)| \le Ce^{-\mu t}, \quad t \ge T_0.$$
 (2.19)

Proposition 2.8. Assume that $f(u) = u^2/2$ in (1.1), and the initial data satisfies

$$u_0(x) = \phi^{\nu}(x) + w_0(x), \tag{2.20}$$

where $w_0(x)$ is periodic with period p>0 and zero average. Then at each time $t_k=kp/(\overline{u}_l-\overline{u}_r),\ k=0,1,2,\cdots$, the solution u^{ν} to (1.1), (1.2) satisfies that

$$u^{\nu}(x,t_k) = \psi^{\nu}_{st_k}(x,t_k), \quad x \in \mathbb{R}; \tag{2.21}$$

and the shift function X^{ν} in Proposition 2.5 satisfies that for $t_k \geqslant T_0$,

$$X^{\nu}(t_k) = st_k. \tag{2.22}$$

Remark 2.9. It can follow from (2.21) and (2.22) that for $t_k \ge T_0$, $u^{\nu}(x, t_k) = \psi^{\nu}_{X^{\nu}}(x, t_k)$, which is compatible with (2.19). And it also implies that the ansatz $\psi^{\nu}_{X^{\nu}}$ is a suitable choice to approach the actual solution u^{ν} .

The rest of this paper proceeds as follows: We first prove Theorems 1.1, 1.3 and 1.4 for viscous shock profiles in Section 3. More precisely, it is shown that Theorem 1.1 follows from Propositions 2.5 and 2.7 easily. Proposition 2.5 for the shift function $X^{\nu}(t)$ is proved in Section 3.1. Proposition 2.7 is proved in Section 3.2, which is independent of Proposition 2.5. In Section 3.3, we prove the result (1) in Theorem 1.3 and Proposition 2.8 for the Burgers' equation. The proof of Theorem 1.3 is completed in Section 3.4, where a strictly convex flux f is constructed such that $X^{\nu}_{\infty,2} \neq 0$. In Section 3.5, we prove Theorem 1.4 for the vanishing viscosity limit for $X^{\nu}_{\infty,2}$. At last, Theorem 1.5 for rarefaction waves is proved in Section 4.

3. Stability of shock profiles

Theorem 1.1 can follow from Lemma 2.1 and Propositions 2.5 and 2.7. In fact, it holds that

$$|u^{\nu}(x,t) - \phi^{\nu}(x - st - X_{\infty}^{\nu})| \leq |u^{\nu}(x,t) - \psi_{X^{\nu}}^{\nu}(x,t)| + |\psi_{X^{\nu}}^{\nu}(x,t) - \phi^{\nu}(x - X^{\nu}(t))| + |\phi^{\nu}(x - X^{\nu}(t)) - \phi^{\nu}(x - st - X_{\infty}^{\nu})|$$

$$\leq Ce^{-\mu t} + |u_l^{\nu}(x,t) - \overline{u}_l| + |u_r^{\nu}(x,t) - \overline{u}_r| + Ce^{-\alpha t}$$

$$\leq Ce^{-\mu t},$$

which proves (1.9). Thus, it remains to prove Propositions 2.5 and 2.7 to finish the proof of Theorem 1.1.

3.1. Shift function.

3.1.1. Existence and uniqueness of the shift function.

For any $\xi \in \mathbb{R}$,

$$\int_{\mathbb{R}} \left(u^{\nu} - \psi_{\xi}^{\nu} \right) (x, T_0) dx = \int_{\mathbb{R}} \left(u^{\nu} - u_l^{\nu} g_{\xi}^{\nu} - u_r^{\nu} (1 - g_{\xi}^{\nu}) \right) (x, T_0) dx.$$

As $\xi \to -\infty$ (resp., $+\infty$), $g_{\xi}^{\nu}(x) = g^{\nu}(x - \xi) \to 0$ (resp., 1), then due to (2.2) and (2.13), one has that $\int_{\mathbb{R}} \left(u^{\nu} - \psi_{\xi}^{\nu}\right)(x, T_0)dx \to +\infty$ (resp., $-\infty$) as $\xi \to -\infty$ (resp., $+\infty$). Thus, there exists an $X_0^{\nu} \in \mathbb{R}$ such that (2.17) holds. And the uniqueness follows from (2.13) and the strict monotonicity of g^{ν} .

Now we prove the existence and uniqueness of $X^{\nu}(t)$ solving the problem (2.15).

Lemma 3.1. The problem (2.15) has a unique C^{∞} solution $X^{\nu}(t): [T_0, +\infty) \to \mathbb{R}$, satisfying

$$|(X^{\nu})'(t) - s| \leqslant Ce^{-\alpha t}, \quad t \geqslant T_0, \tag{3.1}$$

where C > 0 is independent of time t.

Proof. By Lemma 2.4 and (2.13), the denominator of $F^{\nu}(\xi,t)$ satisfies that

$$\int_{\mathbb{R}} (u_l^{\nu} - u_r^{\nu})(x, t)(g_{\xi}^{\nu})'(x)dx \leqslant \frac{\overline{u}_l - \overline{u}_r}{2} \int_{\mathbb{R}} (g_{\xi}^{\nu})'(x)dx$$
$$= -\frac{\overline{u}_l - \overline{u}_r}{2} < 0.$$

Since for any $k \geqslant 1$, $(g^{\nu})^{(k)}$ is integrable and u_l^{ν}, u_r^{ν} are bounded and smooth, F^{ν} is smooth and all the derivatives are bounded. Then the existence, uniqueness and smoothness of X^{ν} can follow from the Cauchy-Lipschitz theorem.

Now we prove (3.1). By Lemmas 2.1 and 2.4, one can get that

$$\int_{-\infty}^{+\infty} (u_l^{\nu} - u_r^{\nu}) (g_{X^{\nu}}^{\nu})'' dx = \int_{-\infty}^{+\infty} (u_l^{\nu} - \overline{u}_l - u_r^{\nu} + \overline{u}_r) (g_{X^{\nu}}^{\nu})'' dx = O\left(e^{-\alpha t}\right),$$

$$\int_{-\infty}^{+\infty} (f(u_l^{\nu}) - f(u_r^{\nu})) (g_{X^{\nu}}^{\nu})' dx = -f(\overline{u}_l) + f(\overline{u}_r) + O\left(e^{-\alpha t}\right),$$

$$\int_{-\infty}^{+\infty} (u_l^{\nu} - u_r^{\nu}) (g_{X^{\nu}}^{\nu})' dx = -\overline{u}_l + \overline{u}_r + O\left(e^{-\alpha t}\right).$$

Therefore, (3.1) holds true.

3.1.2. The limit of the shift function as $t \to +\infty$.

In order to compute $\lim_{t\to +\infty} X^{\nu}(t) - st$ in terms of the initial data $u_0(x)$, the information of the solution $u^{\nu}(x,t)$ for $t\in [0,T_0]$ should be used. However, when $t\in [0,T_0]$, it may fail to find a unique ξ such that $\int_{\mathbb{R}} \left(u^{\nu} - \psi^{\nu}_{\xi}\right)(x,t)dx = 0$ or fail to ensure the denominator of F^{ν} , $\int_{\mathbb{R}} (u^{\nu}_l - u^{\nu}_r)(x,t)(g^{\nu}_{\xi})'(x)dx$, is non-zero. Therefore, we need the following modifications to extend the definition of $X^{\nu}(t)$ on $[0,T_0]$.

For the bounded periodic solutions u_l^{ν} and u_r^{ν} , one can first choose a large number M > 0 such that for all $t \ge 0$,

$$\int_{\mathbb{R}} (u_l^{\nu} - u_r^{\nu})(x, t) (g_{\xi}^{\nu})'(x) dx - M \leq C \int_{\mathbb{R}} |(g_{\xi}^{\nu})'(x)| dx - M$$

$$= C - M < 0.$$
(3.2)

Thanks to (3.2), there exists a unique solution $\hat{X}^{\nu}(t) \in C^{1}[0, T_{0}]$ to the problem

$$\begin{cases} \left(\hat{X}^{\nu}\right)'(t) = \hat{F}^{\nu}\left(\hat{X}^{\nu}(t), t\right), & t \leq T_0, \\ \hat{X}^{\nu}(T_0) = X_0^{\nu}, \end{cases}$$
(3.3)

where

$$\hat{F}^{\nu}(\xi,t) := \frac{\int_{\mathbb{R}} \left[\nu(u_l^{\nu} - u_r^{\nu})(g_{\xi}^{\nu})'' + (f(u_l^{\nu}) - f(u_r^{\nu}))(g_{\xi}^{\nu})' \right] dx}{\int_{\mathbb{R}} (u_l^{\nu} - u_r^{\nu})(g_{\xi}^{\nu})' dx - M}.$$
 (3.4)

The proof of existence and uniqueness of \hat{X}^{ν} is similar to that in Lemma 3.1. Now we claim that

$$M\left(X_0^{\nu} - \hat{X}_0^{\nu}\right) + \int_{\mathbb{R}} \left(u_0(x) - \psi_{\hat{X}_0^{\nu}}^{\nu}(x,0)\right) dx = 0, \tag{3.5}$$

where $\hat{X}_0^{\nu} := \hat{X}^{\nu}(0)$.

Indeed, for any N > 0, one can choose a cut-off function $\varphi_N(x) \in C_0^{\infty}(\mathbb{R})$ satisfying $\varphi_N(x) = 1$, if |x| < N, and $\varphi_N(x) = 0$, if |x| > N + 1. Then by multiplying $\varphi_N(x)$ on each side of (2.14) and integrating by parts, one can get that for any t > 0,

$$\int_{\mathbb{R}} \left(u^{\nu} - \psi_{\hat{X}^{\nu}}^{\nu} \right) (x, t) \varphi_{N}(x) dx \tag{3.6}$$

$$= \int_{\mathbb{R}} \left(u^{\nu} - \psi_{\hat{X}^{\nu}}^{\nu} \right) (x, 0) \varphi_{N}(x) dx + \nu \int_{0}^{t} \int_{\mathbb{R}} \left(u^{\nu} - \psi_{\hat{X}^{\nu}}^{\nu} \right) \varphi_{N}'' dx d\tau
+ \int_{0}^{t} \int_{\mathbb{R}} \left(f(u^{\nu}) - f(\psi_{\hat{X}^{\nu}}^{\nu}) \right) \varphi_{N}' dx d\tau - \int_{0}^{t} \int_{\mathbb{R}} h_{\hat{X}^{\nu}}^{\nu} \varphi_{N} dx d\tau,$$

Thus, by applying Lemmas 2.4 and 3.2, one can take limit $N \to +\infty$ and use the dominated convergence theorem in (3.6) to get that

$$\int_{\mathbb{R}} \left(u^{\nu} - \psi_{\hat{X}^{\nu}}^{\nu} \right)(x, t) dx = \int_{\mathbb{R}} \left(u_0(x) - \psi_{\hat{X}_0^{\nu}}^{\nu}(x, 0) \right) dx - \int_0^t \int_{\mathbb{R}} h_{\hat{X}^{\nu}}^{\nu}(x, \tau) dx d\tau. \tag{3.7}$$

We remark that the use of the test function φ_N here is to avoid the estimates of the derivatives $\partial_x(u^{\nu}-u^{\nu}_l)$ and $\partial_x(u^{\nu}-u^{\nu}_r)$ as $x\to -\infty$ and $+\infty$, respectively. It follows from (2.11) and (3.3) that

$$-\int_{\mathbb{R}} h_{\hat{X}^{\nu}}^{\nu}(x,t)dx = M\frac{d}{dt}\hat{X}^{\nu}(t).$$

This, together with (2.17) and (3.7), yields (3.5).

Now, we define

$$\tilde{X}^{\nu}(t) := \begin{cases} X^{\nu}(t), & t > T_0, \\ \hat{X}^{\nu}(t), & 0 \leqslant t \leqslant T_0. \end{cases}$$
 (3.8)

Then \tilde{X}^{ν} is a Lipschitz continuous curve on $[0, +\infty)$. For $y \in (0, 1), N \in \mathbb{N}^*$ and $t > T_0$, we define the domain

$$\Omega_y^N := \left\{ (x,\tau): \ \tilde{X}^{\nu}(\tau) + (-N+y)p_l \leqslant x \leqslant \tilde{X}^{\nu}(\tau) + (N+y)p_r, \ 0 \leqslant \tau \leqslant t \right\};$$

see Figure 1.

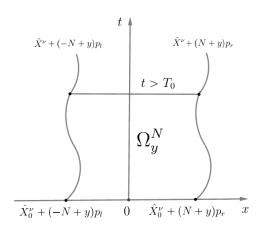


FIGURE 1

It follows from the equations of u_l^{ν} and u_r^{ν} that

$$\iint\limits_{\Omega_{v}^{N}} \left\{ \left(\partial_{t} u_{l}^{\nu} + \partial_{x} f(u_{l}^{\nu}) - \nu \partial_{x}^{2} u_{l}^{\nu} \right) g_{\tilde{X}^{\nu}}^{\nu} + \left(\partial_{t} u_{r}^{\nu} + \partial_{x} f(u_{r}^{\nu}) - \nu \partial_{x}^{2} u_{r}^{\nu} \right) (1 - g_{\tilde{X}^{\nu}}^{\nu}) \right\} dx d\tau = 0.$$

Then integration by parts yields that

$$\iint_{\Omega_y^N} \left\{ -(\tilde{X}^{\nu})'(u_l^{\nu} - u_r^{\nu}) + (f(u_l^{\nu}) - \nu \partial_x u_l^{\nu}) - (f(u_r^{\nu}) - \nu \partial_x u_r^{\nu}) \right\} (g_{\tilde{X}^{\nu}}^{\nu})' dx d\tau$$

$$= A^N(y,t) - A^N(y,0) - B_l^N(y,t) + B_r^N(y,t), \tag{3.9}$$

where

$$A^{N}(y,t) := \int_{\tilde{X}^{\nu}(t)+(N+y)p_{l}}^{\tilde{X}^{\nu}(t)+(N+y)p_{r}} \left[u_{l}^{\nu}(x,t)g_{\tilde{X}^{\nu}}^{\nu}(x) + u_{r}^{\nu}(x,t) \left(1 - g_{\tilde{X}^{\nu}}^{\nu}(x) \right) \right] dx,$$

$$A^{N}(y,0) := \int_{\hat{X}_{0}^{\nu}+(N+y)p_{l}}^{\hat{X}_{0}^{\nu}+(N+y)p_{r}} \left[u_{l}^{\nu}(x,0)g_{\hat{X}_{0}^{\nu}}^{\nu}(x) + u_{r}^{\nu}(x,0)(1 - g_{\hat{X}_{0}^{\nu}}^{\nu}(x)) \right] dx,$$

$$B_{l}^{N}(y,t) := \int_{0}^{t} \left\{ \left(f(u_{l}^{\nu}) - \nu \partial_{x} u_{l}^{\nu} \right) g_{\tilde{X}^{\nu}}^{\nu} + \left(f(u_{r}^{\nu}) - \nu \partial_{x} u_{r}^{\nu} \right) \left(1 - g_{\tilde{X}^{\nu}}^{\nu} \right) - \left(\tilde{X}^{\nu} \right)'(\tau) \left[u_{l}^{\nu} g_{\tilde{X}^{\nu}}^{\nu} + u_{r}^{\nu} \left(1 - g_{\tilde{X}^{\nu}}^{\nu} \right) \right] \right\} \left(\tilde{X}^{\nu}(\tau) + (-N+y)p_{l}, \tau \right) d\tau,$$

$$B_{r}^{N}(y,t) := \int_{0}^{t} \left\{ \left(f(u_{l}^{\nu}) - \nu \partial_{x} u_{l}^{\nu} \right) g_{\tilde{X}^{\nu}}^{\nu} + \left(f(u_{r}^{\nu}) - \nu \partial_{x} u_{r}^{\nu} \right) \left(1 - g_{\tilde{X}^{\nu}}^{\nu} \right) - \left(\tilde{X}^{\nu} \right)'(\tau) \left[u_{l}^{\nu} g_{\tilde{X}^{\nu}}^{\nu} + u_{r}^{\nu} \left(1 - g_{\tilde{X}^{\nu}}^{\nu} \right) \right] \right\} \left(\tilde{X}^{\nu}(\tau) + (N+y)p_{r}, \tau \right) d\tau.$$

$$(3.10)$$

It follows from (2.15) and (3.3) that the left-hand side of (3.9) satisfies that

$$\iint_{\Omega_y^N} \cdots dx d\tau = \iint_{\Omega_y^N \cap \{0 < \tau < T_0\}} \cdots dx d\tau + \iint_{\Omega_y^N \cap \{T_0 < \tau < t\}} \cdots dx d\tau$$

$$\to -M \int_0^{T_0} (\hat{X}^{\nu})'(t) dt + 0 = -M \left(X_0^{\nu} - \hat{X}_0^{\nu} \right) \quad \text{as } N \to +\infty.$$

Thus it remains to evaluate the right-hand side of (3.9) as $N \to +\infty$.

(i) The integrals on $\{\tau = 0\}$ and $\{\tau = t\}$.

Set

$$w_l^{\nu}(x,t) := u_l^{\nu}(x,t) - \overline{u}_l, \quad w_r^{\nu}(x,t) := u_r^{\nu}(x,t) - \overline{u}_r. \tag{3.11}$$

Then it follows from Lemma 2.1 that $\|w_l^{\nu}\|_{L^{\infty}} + \|w_r^{\nu}\|_{L^{\infty}} \leq Ce^{-\alpha t}$. Since w_{0l} and w_{0r} are both of zero average, one has that

$$J^{N}(y,t) =: A^{N}(y,t) - A^{N}(y,0)$$

$$= \int_{(-N+y)p_{l}}^{(N+y)p_{r}} \left[w_{l}^{\nu}(x + \tilde{X}^{\nu}(t),t)g^{\nu}(x) + w_{r}^{\nu}(x + \tilde{X}^{\nu}(t),t)(1 - g^{\nu}(x)) \right] dx \qquad (3.12)$$

$$- \int_{\hat{X}_{0}^{\nu} + (-N+y)p_{l}}^{\hat{X}_{0}^{\nu} + (N+y)p_{r}} \left[w_{0l}(x)g^{\nu}(x - \hat{X}_{0}^{\nu}) + w_{0r}(x) \left(1 - g^{\nu}(x - \hat{X}_{0}^{\nu}) \right) \right] dx$$

$$= O\left(e^{-\alpha t}\right) + \int_{\hat{X}_{0}^{\nu} + yp_{l}}^{\hat{X}_{0}^{\nu} + yp_{l}} \left(w_{0l} - w_{0r})(x) \left(1 - g^{\nu}(x - \hat{X}_{0}^{\nu}) \right) dx$$

$$- \int_{\hat{X}_{0}^{\nu} + yp_{r}}^{\hat{X}_{0}^{\nu} + yp_{r}} \left[w_{0l}(x)g^{\nu}(x - \hat{X}_{0}^{\nu}) + w_{0r}(x) \left(1 - g^{\nu}(x - \hat{X}_{0}^{\nu}) \right) \right] dx$$

$$- \int_{\hat{X}_{0}^{\nu} + yp_{r}}^{\hat{X}_{0}^{\nu} + (N+y)p_{r}} \left(w_{0l} - w_{0r})(x)g^{\nu}(x - \hat{X}_{0}^{\nu}) dx.$$

Then one can get that

$$J(y,t) := \lim_{N \to \infty} J^{N}(y,t)$$

$$= O\left(e^{-\alpha t}\right) + \int_{-\infty}^{\hat{X}_{0}^{\nu} + yp_{l}} (w_{0l} - w_{0r})(x) \left(1 - g^{\nu}(x - \hat{X}_{0}^{\nu})\right) dx$$

$$- \int_{\hat{X}_{0}^{\nu} + yp_{l}}^{\hat{X}_{0}^{\nu} + yp_{r}} \left[w_{0l}(x)g^{\nu}(x - \hat{X}_{0}^{\nu}) + w_{0r}(x) \left(1 - g^{\nu}(x - \hat{X}_{0}^{\nu})\right)\right] dx$$

$$- \int_{\hat{X}_{0}^{\nu} + yp_{r}}^{+\infty} (w_{0l} - w_{0r})(x)g^{\nu}(x - \hat{X}_{0}^{\nu}) dx.$$

$$(3.13)$$

By (3.5), it holds that

$$M\left(X_{0}^{\nu} - \hat{X}_{0}^{\nu}\right) = -\int_{\mathbb{R}} \left[u_{0}(x) - \phi^{\nu}(x - \hat{X}_{0}^{\nu}) - w_{0l}(x)g^{\nu}(x - \hat{X}_{0}^{\nu}) - w_{0r}(x)\left(1 - g^{\nu}(x - \hat{X}_{0}^{\nu})\right)\right] dx$$

$$= -\int_{-\infty}^{0} \left(u_{0} - \phi^{\nu} - w_{0l}\right)(x) dx - \int_{0}^{+\infty} \left(u_{0} - \phi^{\nu} - w_{0r}\right)(x) dx \quad (3.14)$$

$$+ \left(\overline{u}_{l} - \overline{u}_{r}\right)\hat{X}_{0}^{\nu} - \int_{-\infty}^{0} \left(w_{0l} - w_{0r}\right)(x)\left(1 - g^{\nu}(x - \hat{X}_{0}^{\nu})\right) dx$$

$$+ \int_{0}^{+\infty} \left(w_{0l} - w_{0r}\right)(x)g^{\nu}(x - \hat{X}_{0}^{\nu}) dx.$$

This, together with (3.13), yields that

$$J(y,t) = O\left(e^{-\alpha t}\right) - M\left(X_0^{\nu} - \hat{X}_0^{\nu}\right) + (\overline{u}_l - \overline{u}_r)\hat{X}_0^{\nu}$$
$$- \int_{-\infty}^{0} \left(u_0 - \phi^{\nu} - w_{0l}\right)(x)dx - \int_{0}^{+\infty} \left(u_0 - \phi^{\nu} - w_{0r}\right)(x)dx$$
$$+ \int_{0}^{\hat{X}_0^{\nu} + yp_l} w_{0l}(x)dx - \int_{0}^{\hat{X}_0^{\nu} + yp_r} w_{0r}(x)dx.$$

It is noted that for i = l, r, since w_{0i} has zero average, $\int_0^y w_{0i}(x) dx$ is periodic with respective to y with period p_i . Therefore,

$$\int_{0}^{1} \int_{0}^{\hat{X}_{0}^{\nu} + yp_{i}} w_{0i}(x) dx dy = \frac{1}{p_{i}} \int_{0}^{p_{i}} \int_{0}^{\hat{X}_{0}^{\nu} + y} w_{0i}(x) dx dy$$
$$= \frac{1}{p_{i}} \int_{0}^{p_{i}} \int_{0}^{y} w_{0i}(x) dx dy.$$

Thus one can get that

$$\int_{0}^{1} J(y,t)dy = O\left(e^{-\alpha t}\right) - M\left(X_{0}^{\nu} - \hat{X}_{0}^{\nu}\right) + (\overline{u}_{l} - \overline{u}_{r})\hat{X}_{0}^{\nu}$$

$$- \int_{-\infty}^{0} \left(u_{0} - \phi^{\nu} - w_{0l}\right)(x)dx - \int_{0}^{+\infty} \left(u_{0} - \phi^{\nu} - w_{0r}\right)(x)dx$$

$$+ \frac{1}{n_{l}} \int_{0}^{p_{l}} \int_{0}^{y} w_{0l}(x)dxdy - \frac{1}{n_{r}} \int_{0}^{p_{r}} \int_{0}^{y} w_{0r}(x)dxdy.$$
(3.15)

(ii) The integrals on two sides.

Since u_l^{ν} is periodic, it holds that

$$B_l^N(y,t) = \int_0^t \left\{ \left(f(u_l^{\nu}) - \nu \partial_x u_l^{\nu} \right) \left(\tilde{X}^{\nu}(\tau) + y p_l, \tau \right) g^{\nu} \left((-N+y) p_l \right) \right.$$

$$\left. - \left(\tilde{X}^{\nu} \right)'(\tau) u_l^{\nu} \left(\tilde{X}^{\nu}(\tau) + y p_l, \tau \right) \right.$$

$$\left. + \left[\cdots \right] \left(1 - g_{\tilde{X}^{\nu}}^{\nu} \right) \left(\tilde{X}^{\nu}(\tau) + (-N+y) p_l, \tau \right) \right\} d\tau,$$

$$(3.16)$$

where $[\cdots]$ denotes the remaining terms which are bounded. Then taking the limit $N \to +\infty$ in (3.16) and using Lemma 2.4, one can get that

$$\lim_{N \to +\infty} \int_0^1 B_l^N(y,t) dy = \int_0^t \frac{1}{p_l} \int_0^{p_l} f(u_l^{\nu}) \left(\tilde{X}^{\nu} + x, \tau \right) dx d\tau - \int_0^t (\tilde{X}^{\nu})'(\tau) \overline{u}_l d\tau$$
$$= \int_0^t \frac{1}{p_l} \int_0^{p_l} f(u_l^{\nu})(x,\tau) dx d\tau - \overline{u}_l \left(\tilde{X}^{\nu}(t) - \hat{X}_0^{\nu} \right).$$

Similarly, it holds that

$$\lim_{N\to+\infty} \int_0^1 B_r^N(y,t) dy = \int_0^t \frac{1}{p_r} \int_0^{p_r} f(u_r^{\nu})(x,\tau) dx d\tau - \overline{u}_r \left(\tilde{X}^{\nu}(t) - \hat{X}_0^{\nu} \right).$$

Now, with the calculations in (i) and (ii), one can integrate the equation (3.9) with respect to y over (0,1), and then let $N \to +\infty$, to get that for any $t > T_0$,

$$\int_{0}^{1} J(y,t)dy + (\overline{u}_{l} - \overline{u}_{r}) \left(\tilde{X}^{\nu}(t) - \hat{X}_{0}^{\nu} \right)
= \int_{0}^{t} \left[\frac{1}{p_{l}} \int_{0}^{p_{l}} f(u_{l}^{\nu})(x,\tau)dx - \frac{1}{p_{r}} \int_{0}^{p_{r}} f(u_{r}^{\nu})(x,\tau)dx \right] d\tau - M \left(X_{0}^{\nu} - \hat{X}_{0}^{\nu} \right).$$
(3.17)

Note also that for i = l, r,

$$\int_0^t \frac{1}{p_i} \int_0^{p_i} f(u_i^{\nu}) dx d\tau = \int_0^t \frac{1}{p_i} \int_0^{p_i} \left(f(u_i^{\nu}) - f(\overline{u}_i) \right) dx d\tau + f(\overline{u}_i) t$$

$$= \int_0^{+\infty} \frac{1}{p_i} \int_0^{p_i} \left(f(u_i^{\nu}) - f(\overline{u}_i) \right) dx d\tau + O\left(e^{-\alpha t}\right) + f(\overline{u}_i) t,$$

where Lemma 2.1 is used. Then it can follow from (3.15) and (3.17) that for $t > T_0$,

$$X^{\nu}(t) - st = \tilde{X}^{\nu}(t) - st = O\left(e^{-\alpha t}\right) + X_{\infty}^{\nu},$$
 (3.18)

where X_{∞}^{ν} is defined in Theorem 1.1. The proof of Proposition 2.5 is finished.

3.2. Decay to ansatz.

In this section, we will prove Proposition 2.7. First, $u^{\nu}(x,t)$ will be proved to be close to $u_l^{\nu}(x,t)$ (resp., $u_r^{\nu}(x,t)$) in the region $x < st - N_{\varepsilon}$ (resp. $x > st - N_{\varepsilon}$) with large enough t and N_{ε} (independent of time); see Proposition 3.4. Then motivated by [16], the equation of the anti-derivative variable of $u^{\nu} - \psi_{X^{\nu}}^{\nu}$ is studied and the comparison principle is applied to prove Proposition 2.7.

3.2.1. Time-independent estimates (Proposition 3.4).

The following result follows directly from Lemma 2.3.

Lemma 3.2. Under the assumptions of Theorem 1.1, there holds that

$$\left| u^{\nu}(x,t) - \psi_{\xi}^{\nu}(x,t) \right| \leqslant C(t)e^{\beta|\xi|}e^{-\beta|x-\xi|} \qquad \forall \xi, x \in \mathbb{R}, t \geqslant 0,$$

where C(t) > 0 is bounded on any compact subset of $[0, +\infty)$.

Then by Lemmas 2.3 and 3.2, for any $x \in \mathbb{R}, t \ge 0$, one can define the anti-derivative variables:

$$U_l^{\nu}(x,t) := \int_{-\infty}^x (u^{\nu} - u_l^{\nu})(y,t)dy, \tag{3.19}$$

$$U_r^{\nu}(x,t) := \int_x^{+\infty} (u^{\nu} - u_r^{\nu})(y,t)dy, \tag{3.20}$$

$$\check{U}_{\xi}^{\nu}(x,t) := \int_{-\infty}^{x} (u^{\nu} - \psi_{\xi}^{\nu})(y,t)dy, \tag{3.21}$$

$$\hat{U}_{\xi}^{\nu}(x,t) := \int_{x}^{+\infty} (u^{\nu} - \psi_{\xi}^{\nu})(y,t)dy. \tag{3.22}$$

Lemma 3.3. For any C^{∞} curve $\xi(t): [1, +\infty) \to \mathbb{R}$ with bounded derivatives, the functions $U_l^{\nu}, U_r^{\nu}, \check{U}_{\xi}^{\nu}$ and \hat{U}_{ξ}^{ν} defined above satisfy the following equations:

$$\partial_t U_l^{\nu} - \nu \partial_x^2 U_l^{\nu} = f(u_l^{\nu}) - f(u^{\nu}), \qquad x \in \mathbb{R}, t > 1, \tag{3.23}$$

$$\partial_t U_l^{\nu} - \nu \partial_x^2 U_l^{\nu} = f(u_l^{\nu}) - f(u^{\nu}), \qquad x \in \mathbb{R}, t > 1,
\partial_t U_r^{\nu} - \nu \partial_x^2 U_r^{\nu} = f(u^{\nu}) - f(u_r^{\nu}), \qquad x \in \mathbb{R}, t > 1,$$
(3.23)

$$\partial_t \check{U}^{\nu}_{\xi} - \nu \partial_x^2 \check{U}^{\nu}_{\xi} = f(\psi^{\nu}_{\xi}) - f(u^{\nu}) - \int_{-\infty}^x h^{\nu}_{\xi}(y, t) dy, \quad x \in \mathbb{R}, t > 1,$$
 (3.25)

$$\partial_t \hat{U}^{\nu}_{\xi} - \nu \partial_x^2 \hat{U}^{\nu}_{\xi} = f(u^{\nu}) - f(\psi^{\nu}_{\xi}) - \int_x^{+\infty} h^{\nu}_{\xi}(y, t) dy, \quad x \in \mathbb{R}, t > 1,$$
 (3.26)

where the derivatives appearing in these equations are all continuous in $\mathbb{R} \times [1, +\infty)$.

Proof. Here we prove only (3.23) and (3.25), since the proofs of the other two are similar.

To prove (3.23), for any T > 1, we consider the following problem

$$\begin{cases}
\partial_t V - \nu \partial_x^2 V = f(u_l^{\nu}) - f(u^{\nu}), & x \in \mathbb{R}, 1 < t \leq T, \\
V(x, 1) = U_l^{\nu}(x, 1).
\end{cases}$$
(3.27)

It follows from Lemma 2.3 that

$$\begin{cases} |f(u_l^{\nu}) - f(u^{\nu})| \leqslant C(T)e^{\beta x} & \forall x \in \mathbb{R}, 1 < t \leqslant T, \\ |U_l^{\nu}(x, 1)| \leqslant Ce^{\beta x} & \forall x \in \mathbb{R}. \end{cases}$$
(3.28)

Note that

$$e^{\beta|x|}\leqslant C(T)e^{\frac{1}{4\nu T}|x|^2}$$

and the initial data $U_I^{\nu}(x,1)$ and the source term $f(u_I^{\nu}) - f(u^{\nu})$ are smooth functions, then by the standard parabolic theories (see [6, Chapter 1, Theorem 12]), the function

$$V(x,t) = \int_0^{t-1} K^{\tau}(\cdot) * (f(u_l^{\nu}) - f(u^{\nu}))(\cdot, t - \tau) d\tau + K^{t-1}(\cdot) * U_l^{\nu}(\cdot, 1)$$
 (3.29)

solves (3.27) and all the derivatives of V appearing in the equation exist and are continuous in $\mathbb{R} \times [1,T]$, where $K^t(x) := (2\pi\nu t)^{-\frac{1}{2}}e^{-\frac{x^2}{4\nu t}}$ is the heat kernel. It then follows from (3.28) and (3.29) that V(x,t) vanishes as $x \to -\infty$. Then by (3.29) and the equations of u^{ν} and u^{ν}_{l} , it holds that

$$\partial_x V(x,t) = \int_0^{t-1} \left[\partial_x K^{\tau} * (f(u_l^{\nu}) - f(u)) \right] (x,t-\tau) d\tau + \left[K^{t-1} * (u-u_l^{\nu}) \right] (x,1)$$

$$= (u-u_l^{\nu})(x,t), \qquad x \in \mathbb{R}, 1 \le t \le T,$$

which implies that $V(x,t) = U_l^{\nu}(x,t)$ for all $x \in \mathbb{R}$ and $1 \le t \le T$. And since T > 1 is arbitrary, (3.23) holds true.

(2) Now we prove (3.25). By integrating (2.11) with respect to the spatial variable on $(-\infty, x)$, one can get from Lemmas 2.1 and 2.4 that

$$\int_{-\infty}^{x} h_{\xi}^{\nu} dy = \left(f(\psi_{\xi}^{\nu}) - f(u_{l}^{\nu}) \right) g_{\xi}^{\nu} + \left(f(\psi_{\xi}^{\nu}) - f(u_{r}^{\nu}) \right) (1 - g_{\xi}^{\nu})$$

$$- 2\nu (u_{l}^{\nu} - u_{r}^{\nu}) (g_{\xi}^{\nu})' + \int_{-\infty}^{x} (f(u_{l}^{\nu}) - f(u_{r}^{\nu})) (g_{\xi}^{\nu})' dy$$

$$- \xi'(t) \int_{-\infty}^{x} (u_{l}^{\nu} - u_{r}^{\nu}) (g_{\xi}^{\nu})' dy + \nu \int_{-\infty}^{x} (u_{l}^{\nu} - u_{r}^{\nu}) (g_{\xi}^{\nu})'' dy,$$

is smooth. Then it follows from Lemmas 2.1, 2.4 and $\psi_{\xi}^{\nu} - u_{l}^{\nu} = -(u_{l}^{\nu} - u_{r}^{\nu}) (1 - g_{\xi}^{\nu})$ that for any $t \ge 1$,

$$\left| \int_{-\infty}^{x} h_{\xi}^{\nu}(y,t) dy \right| \leq C \left(1 - g_{\xi}^{\nu}(x) + \left| (g_{\xi}^{\nu})'(x) \right| + \int_{-\infty}^{x} \left| (g_{\xi}^{\nu})' \right| dy + \int_{-\infty}^{x} \left| (g_{\xi}^{\nu})'' \right| dy \right).$$

Note that $\int_{-\infty}^{x} \left| (g_{\xi}^{\nu})' \right| dy = 1 - g_{\xi}^{\nu}$. And by $(g^{\nu})'' = \frac{1}{\overline{u}_{l} - \overline{u}_{r}} (f'(\phi^{\nu}) - s) (\phi^{\nu})'$, there exists a unique point $x_{0} \in \mathbb{R}$ such that $(g^{\nu})''(x) < 0$ for $x < x_{0}$, and $(g^{\nu})''(x) > 0$ for $x > x_{0}$. Then $\int_{-\infty}^{x} \left| (g_{\xi}^{\nu})'' \right| (y) dy = -(g_{\xi}^{\nu})'(x)$ if $x < x_{0} + \xi$. Hence, it follows from Lemma 2.4 that

$$\left| \int_{-\infty}^{x} h_{\xi}^{\nu}(y, t) dy \right| \leqslant Ce^{\beta x} \qquad \forall x \in \mathbb{R}, t \geqslant 1.$$
 (3.30)

By Lemma 3.2, one can verify easily that

$$\left| \check{U}_{\xi(1)}^{\nu}(x,1) \right| \leqslant Ce^{\beta x} \qquad \forall x \in \mathbb{R}.$$
 (3.31)

Now we consider the problem:

$$\begin{cases} \partial_t \check{V} - \nu \partial_x^2 \check{V} = \check{H}^{\nu} := f(\psi_{\xi}^{\nu}) - f(u^{\nu}) - \int_{-\infty}^x h_{\xi}^{\nu}(y, t) dy, & x \in \mathbb{R}, 1 < t \leqslant T, \\ \check{V}(x, 1) = \check{U}_{\xi(1)}^{\nu}(x, 1), & x \in \mathbb{R}. \end{cases}$$
(3.32)

For any T > 1, it follows from Lemma 3.2 and (3.30) that

$$|\check{H}^{\nu}(x,t)| \leqslant C(T)e^{\beta x} \qquad \forall x \in \mathbb{R}, 1 < t \leqslant T.$$
 (3.33)

Then similar to the proof in (1), since the initial data $\check{U}_{\xi(1)}^{\nu}(x,1)$ is smooth and satisfies (3.31), and the source term \check{H}^{ν} is smooth and satisfies (3.33), one can obtain that the function

$$\check{V}(x,t) = \int_0^{t-1} K^{\tau}(\cdot) * \check{H}^{\nu}(\cdot, t - \tau) d\tau + K^{t-1}(\cdot) * \check{U}^{\nu}_{\xi(1)}(\cdot, 1)$$
 (3.34)

solves (3.32) and all the derivatives of V appearing in the equation exist and are continuous in $\mathbb{R} \times [1,T]$. It follows from (3.33) and (3.34) that $\check{V}(x,t)$ vanishes as $x \to -\infty$. Then (3.34) and the equation of $\psi_{\mathcal{E}}^{\nu}$ yield

$$\partial_t \left(u^{\nu} - \psi_{\xi}^{\nu} \right) - \nu \partial_x^2 \left(u^{\nu} - \psi_{\xi}^{\nu} \right) = \partial_x \left(f(\psi_{\xi}^{\nu}) - f(u^{\nu}) - \int_{-\infty}^x h_{\xi}^{\nu}(y, t) dy \right)$$
$$= \partial_x \check{H}^{\nu}.$$

And then

$$\partial_x \check{V}(x,t) = \int_0^{t-1} \partial_x K^{\tau}(\cdot) * \check{H}^{\nu}(\cdot, t - \tau) d\tau + K^{t-1}(\cdot) * \left(u^{\nu} - \psi_{\xi}^{\nu}\right)(\cdot, 1)$$
$$= \left(u^{\nu} - \psi_{\xi}^{\nu}\right)(x, t) \qquad \forall x \in \mathbb{R}, 1 < t \leqslant T,$$

which implies $\check{V} = \check{U}^{\nu}_{\varepsilon}$.

Now we choose a fixed small number $\varepsilon_0 > 0$ such that

$$f'(\overline{u}_l - 2\varepsilon_0) - s > 0$$
 and $f'(\overline{u}_r + 2\varepsilon_0) - s < 0.$ (3.35)

Then it can follow from Lemma 2.1 that there exists $T_1 > T_0$ large enough such that

$$u_l^{\nu}(x,t) > \overline{u}_l - \varepsilon_0 \text{ and } u_r^{\nu}(x,t) < \overline{u}_r + \varepsilon_0 \qquad \forall x \in \mathbb{R}, \ t > T_1,$$
 (3.36)

where T_0 is the number chosen in (2.13).

For later use, we define

$$a(v,w) := \int_0^1 f'(w + \rho(v - w)) d\rho, \tag{3.37}$$

$$b(v,w) := \int_0^1 f''(w + \rho(v - w)) d\rho. \tag{3.38}$$

Now, we give the results of the time-independent estimates of $u^{\nu} - u^{\nu}_{l}$ and $u^{\nu} - u^{\nu}_{r}$.

Proposition 3.4. Under the assumptions of Theorem 1.1. There exists $T_2 > T_1$ such that for any $\varepsilon > 0$, there exists $N = N(\varepsilon) > 0$, independent of time t, such that

$$|u^{\nu}(x,t) - u^{\nu}_{l}(x,t)| \leqslant \varepsilon \qquad \forall t > T_{2}, x < st - N, \tag{3.39}$$

$$|u^{\nu}(x,t) - u^{\nu}_{l}(x,t)| \leq \varepsilon \qquad \forall t > T_{2}, x < st - N,$$

$$|u^{\nu}(x,t) - u^{\nu}_{r}(x,t)| \leq \varepsilon \qquad \forall t > T_{2}, x > st + N.$$

$$(3.39)$$

Proof. We prove (3.39) only, since the proof of (3.40) is similar. And the proof will be divided into four steps.

Step 1. For any $\varepsilon > 0$, we will prove that there exist $T_2 > T_1$, independent of ε , and $N_1 = N_1(\varepsilon) > 0$ such that

$$U_l^{\nu}(x,t) < \varepsilon \quad \forall t > T_2, \ x < st - N_1,$$

where U_I^{ν} is defined in (3.19).

By (3.35), one can define a constant

$$\tilde{\beta} := f'(\overline{u}_l - 2\varepsilon_0) - s > 0. \tag{3.41}$$

And then we define the function

$$\tilde{u}(x,t) := M_1 e^{\tilde{\beta}(x-st)} + u_l^{\nu}(x,t), \quad x \in \mathbb{R}, t > 0,$$
(3.42)

where the constant $M_1 > 1$ will be determined later (see (3.47)). Then by the equation of u_l^{ν} , one has that

$$\partial_t \tilde{u} - \nu \partial_x^2 \tilde{u} + \partial_x f(\tilde{u}) = \tilde{h} := -\tilde{\beta} s M_1 e^{\tilde{\beta}(x-st)} - \nu \tilde{\beta}^2 M_1 e^{\tilde{\beta}(x-st)} + \partial_x \left(f(\tilde{u}) - f(u_l^{\nu}) \right). \tag{3.43}$$

Since f is strictly convex, (3.36) implies that

$$f'(\tilde{u}) \geqslant f'(u_l^{\nu}) \geqslant f'(\overline{u}_l - \varepsilon_0) \quad \forall x \in \mathbb{R}, t \geqslant T_1.$$

Hence, for the given constant M_1 , if $t \ge T_1$, the following two inequalities hold.

(1) If x satisfies $M_1 e^{\tilde{\beta}(x-st)} \geqslant 1$, then it holds that

$$\partial_{x} \left(f(\tilde{u}) - f(u_{l}^{\nu}) \right) = \left(f'(\tilde{u}) - f'(u_{l}^{\nu}) \right) \left(\tilde{\beta} M_{1} e^{\tilde{\beta}(x-st)} + \partial_{x} u_{l}^{\nu} \right) + f'(u_{l}^{\nu}) \tilde{\beta} M_{1} e^{\tilde{\beta}(x-st)}$$

$$\geq \left(f'(\tilde{u}) - f'(u_{l}^{\nu}) \right) \left(\tilde{\beta} - |\partial_{x} u_{l}^{\nu}| \right) + f'(\overline{u}_{l} - \varepsilon_{0}) \tilde{\beta} M_{1} e^{\tilde{\beta}(x-st)}.$$

Then by (3.43), Lemma 2.4 and $0 < \nu \le 1$, one has that

$$\tilde{h} \geq (f'(\tilde{u}) - f'(u_l^{\nu})) \left(\tilde{\beta} - |\partial_x u_l^{\nu}| \right) + \tilde{\beta} M_1 e^{\tilde{\beta}(x-st)} \left(f'(\overline{u}_l - \varepsilon_0) - (s + \tilde{\beta}) \right)
\geq (f'(\tilde{u}) - f'(u_l^{\nu})) \left(\tilde{\beta} - Ce^{-\alpha t} \right) + \tilde{\beta} M_1 e^{\tilde{\beta}(x-st)} \left(f'(\overline{u}_l - \varepsilon_0) - f'(\overline{u}_l - 2\varepsilon_0) \right)
\geq (f'(\tilde{u}) - f'(u_l^{\nu})) \left(\tilde{\beta} - Ce^{-\alpha t} \right).$$

(2) If x satisfies $M_1 e^{\tilde{\beta}(x-st)} < 1$, one has $0 < \tilde{u} - u_l^{\nu} \leq 1$. Then it holds that

$$\partial_{x} \left(f(\tilde{u}) - f(u_{l}^{\nu}) \right) = f'(\tilde{u}) \tilde{\beta} M_{1} e^{\tilde{\beta}(x-st)} + \left(f'(\tilde{u}) - f'(u_{l}^{\nu}) \right) \partial_{x} u_{l}^{\nu}
= f'(\tilde{u}) \tilde{\beta} M_{1} e^{\tilde{\beta}(x-st)} + f''(\cdot) (\tilde{u} - u_{l}^{\nu}) \partial_{x} u_{l}^{\nu}
\geqslant f'(\overline{u}_{l} - \varepsilon_{0}) \tilde{\beta} M_{1} e^{\tilde{\beta}(x-st)} - C M_{1} e^{\tilde{\beta}(x-st)} |\partial_{x} u_{l}^{\nu}|.$$

This yields that

$$\begin{split} \tilde{h} &\geqslant \tilde{\beta} M_{1} e^{\tilde{\beta}(x-st)} \left(f'(\overline{u}_{l} - \varepsilon_{0}) - (s + \tilde{\beta}) \right) - C M_{1} e^{\tilde{\beta}(x-st)} \left| \partial_{x} u_{l}^{\nu} \right| \\ &\geqslant M_{1} e^{\tilde{\beta}(x-st)} \left[\tilde{\beta} \left(f'(\overline{u}_{l} - \varepsilon_{0}) - (s + \tilde{\beta}) \right) - C e^{-\alpha t} \right] \\ &\geqslant M_{1} e^{\tilde{\beta}(x-st)} \left[\tilde{\beta} \left(f'(\overline{u}_{l} - \varepsilon_{0}) - f'(\overline{u}_{l} - 2\varepsilon_{0}) \right) - C e^{-\alpha t} \right] \\ &\geqslant M_{1} e^{\tilde{\beta}(x-st)} \left(\tilde{\beta} c_{0} \varepsilon_{0} - C e^{-\alpha t} \right), \end{split}$$

where $c_0 := \min f'' > 0$.

As a result of (1) and (2), there exists a constant $T_2 > T_1$, independent of either M_1 or ε , such that

$$\tilde{h} = \partial_t \tilde{u} - \nu \partial_x^2 \tilde{u} + \partial_x f(\tilde{u}) > 0 \qquad \forall x \in \mathbb{R}, t \geqslant T_2.$$

Set $\tilde{U}(x,t):=\int_{-\infty}^x (u^{\nu}-\tilde{u})(y,t)dy$. Then as for the proof of Lemma 3.3, one can prove that

$$\partial_t \tilde{U} - \nu \partial_x^2 \tilde{U} + (f(u^{\nu}) - f(\tilde{u})) = -\int_{-\infty}^x \tilde{h}(y, t) dy, \qquad x \in \mathbb{R}, t > T_2,$$

which implies that

$$\partial_t \tilde{U} - \nu \partial_x^2 \tilde{U} + a(u^{\nu}, \tilde{u}) \partial_x \tilde{U} < 0 \qquad \forall x \in \mathbb{R}, t > T_2, \tag{3.44}$$

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where a(u, v) is defined by (3.37). By Lemma 3.2, there exists $N_0 > 0$ such that

$$|U_l^{\nu}(x, T_2)| = \left| \int_{-\infty}^x (u^{\nu} - u_l^{\nu})(y, T_2) dy \right| \le \varepsilon/2 \quad \forall x \le -N_0.$$
 (3.45)

For this N_0 , it can also follow from Lemma 3.2 that one can define a constant

$$B := \sup_{x \geqslant -N_0} \left| \int_{-N_0}^x (u^{\nu} - u_r^{\nu})(y, T_2) dy \right| < +\infty.$$
 (3.46)

It is noted that the given constants $\tilde{\beta}$, T_2 , N_0 and B are all independent of M_1 , thus one can choose $M_1 > 0$ large enough such that

$$\int_{-\infty}^{-N_0} (u_l^{\nu} - \tilde{u})(y, T_2) dy = -\frac{M_1}{\tilde{\beta}} e^{-\tilde{\beta}(N_0 + sT_2)} < -B.$$
 (3.47)

Now we claim that

Claim 1.

$$\tilde{U}(x,T_2) = \int_{-\infty}^{x} (u^{\nu} - \tilde{u})(y,T_2) dy \leqslant \varepsilon/2 \quad \forall x \in \mathbb{R}.$$

In fact, if $x \leq -N_0$, then (3.45) implies that

$$\int_{-\infty}^{x} (u^{\nu} - \tilde{u})(y, T_2) dy \leqslant \int_{-\infty}^{x} (u^{\nu} - u_l^{\nu})(y, T_2) dy \leqslant \varepsilon/2.$$

And if $x > -N_0$, it follows from (3.45) and (3.46) that

$$\int_{-\infty}^{x} (u^{\nu} - \tilde{u})(y, T_{2}) dy = \int_{-\infty}^{-N_{0}} (u^{\nu} - u^{\nu}_{l}) + \int_{-\infty}^{-N_{0}} (u^{\nu}_{l} - \tilde{u}) + \int_{-N_{0}}^{x} (u^{\nu} - u^{\nu}_{r}) + \int_{-N_{0}}^{x} (u^{\nu}_{r} - \tilde{u})$$

$$\leq \varepsilon/2 - B + B + 0 = \varepsilon/2,$$

which proves Claim 1.

Combining (3.44) with *Claim* 1, and using the maximum principle [16, Lemma 1], one can obtain that

$$\tilde{U}(x,t) \leqslant \varepsilon/2 \qquad \forall x \in \mathbb{R}, t \geqslant T_2,$$

which implies that

$$U_l^{\nu}(x,t) = \int_{-\infty}^x (u^{\nu} - u_l^{\nu})(y,t)dy = \tilde{U}(x,t) + \frac{M_1}{\tilde{\beta}} e^{\tilde{\beta}(x-st)} \leqslant \varepsilon,$$

if $t \ge T_2$ and $x - st < -N_1$ with $N_1 > 0$ large enough.

Step 2. In this step, it is aimed to construct a "sub-solution" ψ_{ξ}^{ν} to (1.1) such that the anti-derivative variable of $u^{\nu} - \psi_{\xi}^{\nu}$ has the lower bound $-\varepsilon$ (see (3.55)). The idea is to find a C^{∞} curve $\xi(t): [T_2, +\infty) \to \mathbb{R}$ such that the ansatz ψ_{ξ}^{ν} defined by (2.8) satisfies that

$$h_{\xi}^{\nu} = \partial_t \psi_{\xi}^{\nu} + \partial_x f(\psi_{\xi}^{\nu}) - \nu \partial_x^2 \psi_{\xi}^{\nu} < 0 \qquad \forall x \in \mathbb{R}, t > T_2, \tag{3.48}$$

with the proper initial data (3.53).

For two given constants $M_2 > 0$ and d > 0, where M_2 will be determined in this step, and d will be determined in the next step, we define a C^{∞} curves $\xi(t)$: $[T_2, +\infty) \to \mathbb{R}$, which solves the following problem

$$\begin{cases} \xi'(t) = s - M_2 e^{-\alpha t}, & t > T_2, \\ \xi(T_2) = -d. \end{cases}$$
 (3.49)

Then by (3.49), there exists a constant D > d, depending on α, T_2, d and M_2 , such that

$$\xi(t) \in [st - D, st + D] \quad \forall t \geqslant T_2. \tag{3.50}$$

Now we calculate the source term h_{ε}^{ν} . It follows from (2.12) and (2.13) that for $t \geq T_2$,

$$h_{\xi}^{\nu} = (u_{l}^{\nu} - u_{r}^{\nu}) \left(\xi'(t) - s + f'(\phi_{\xi}^{\nu}) - f'(\psi_{\xi}^{\nu}) + 2\nu \frac{\partial_{x} u_{l}^{\nu} - \partial_{x} u_{r}^{\nu}}{u_{l}^{\nu} - u_{r}^{\nu}} \right) \left| (g_{\xi}^{\nu})' \right| - (u_{l}^{\nu} - u_{r}^{\nu}) \left(b(\psi_{\xi}^{\nu}, u_{l}^{\nu}) \partial_{x} u_{l}^{\nu} - b(\psi_{\xi}^{\nu}, u_{r}^{\nu}) \partial_{x} u_{r}^{\nu} \right) g_{\xi}^{\nu} (1 - g_{\xi}^{\nu}),$$

where b(u, v) is defined in (3.38). Then by Lemma 2.1 and (2.4), one has that for $t \ge T_2$,

$$h_{\xi}^{\nu} \leq (u_{l}^{\nu} - u_{r}^{\nu}) \left(\xi'(t) - s + f'(\phi_{\xi}^{\nu}) - f'(\psi_{\xi}^{\nu}) + 2\nu \frac{\partial_{x} u_{l}^{\nu} - \partial_{x} u_{r}^{\nu}}{u_{l}^{\nu} - u_{r}^{\nu}} \right) \left| (g_{\xi}^{\nu})' \right|$$

$$+ C(u_{l}^{\nu} - u_{r}^{\nu}) \left(|\partial_{x} u_{r}^{\nu}| + |\partial_{x} u_{l}^{\nu}| \right) \left| (g_{\xi}^{\nu})' \right|$$

$$\leq (u_{l}^{\nu} - u_{r}^{\nu}) \left| (g_{\xi}^{\nu})' \right| \left[-M_{2} e^{-\alpha t} + C \left| \phi_{\xi}^{\nu} - \psi_{\xi}^{\nu} \right| + C \left(|\partial_{x} u_{r}^{\nu}| + |\partial_{x} u_{l}^{\nu}| \right) \right].$$

Note that $\left|\phi_{\xi}^{\nu}-\psi_{\xi}^{\nu}\right| \leq \left|\overline{u}_{l}-u_{l}^{\nu}\right|g_{\xi}^{\nu}+\left|\overline{u}_{r}-u_{r}^{\nu}\right|\left(1-g_{\xi}^{\nu}\right) \leq Ce^{-\alpha t}$ for all $x \in \mathbb{R}$. Then if $M_{2}>0$ is large enough, it holds that

$$h_{\xi}^{\nu}(x,t) \leq (u_l^{\nu} - u_r^{\nu}) |(g_{\xi}^{\nu})'| (-M_2 + C) e^{-\alpha t} < 0 \qquad \forall x \in \mathbb{R}, t > T_2.$$

Therefore, for $M_2 > 0$ large enough, (3.48) is fulfilled with the ξ constructed in (3.49).

Step 3. In this step, we will prove that there exists $N_2 = N_2(\varepsilon) > 0$ such that

$$U_l^{\nu}(x,t) > -\varepsilon \quad \forall t > T_2, \ x < st - N_2. \tag{3.51}$$

For the constants N_0 and B defined in (3.45) and (3.46), one can choose the constant $d = \xi(T_2) > 0$ (see (3.49)) large enough such that

$$\int_{-\infty}^{-N_0} \left(u_l^{\nu} - \psi_{-d}^{\nu} \right) (x, T_2) dx + \int_{-N_0}^{+\infty} \left(u_r^{\nu} - \psi_{-d}^{\nu} \right) (x, T_2) dx$$

$$= \int_{-\infty}^{-N_0} \left(u_l^{\nu} - u_r^{\nu} \right) (x, T_2) \left(1 - g^{\nu}(x+d) \right) dx - \int_{-N_0}^{+\infty} \left(u_l^{\nu} - u_r^{\nu} \right) (x, T_2) g^{\nu}(x+d) dx$$

$$> B. \tag{3.52}$$

Then we claim that

 $Claim\ 2.$

$$\check{U}^{\nu}_{\xi(T_2)}(x, T_2) = \int_{-\infty}^{x} \left(u^{\nu} - \psi^{\nu}_{-d} \right) (y, T_2) dy \geqslant -\varepsilon/2 \qquad \forall x \in \mathbb{R}. \tag{3.53}$$

where U_{ξ}^{ν} is defined in (3.21).

In fact, if $x \leq -N_0$, then it follows from (3.45) that

$$\int_{-\infty}^{x} \left(u^{\nu} - \psi_{-d}^{\nu} \right) (y, T_2) dy \geqslant \int_{-\infty}^{x} \left(u^{\nu} - u_l^{\nu} \right) (y, T_2) dy \geqslant -\varepsilon/2.$$

And if $x > -N_0$, then by (3.45), (3.46) and (3.52), one can get that

$$\int_{-\infty}^{x} \left(u^{\nu} - \psi_{-d}^{\nu} \right) = \int_{-\infty}^{-N_0} \left(u^{\nu} - u^{\nu}_{l} \right) + \int_{-\infty}^{-N_0} \left(u^{\nu}_{l} - \psi_{-d}^{\nu} \right) + \int_{-N_0}^{x} \left(u^{\nu} - u^{\nu}_{r} \right) + \int_{-N_0}^{x} \left(u^{\nu}_{r} - \psi_{-d}^{\nu} \right) \\
\geqslant -\varepsilon/2 + \int_{-\infty}^{-N_0} \left(u^{\nu}_{l} - \psi_{-d}^{\nu} \right) - B + \int_{-N_0}^{+\infty} \left(u^{\nu}_{r} - \psi_{-d}^{\nu} \right) \geqslant -\varepsilon/2.$$

Thus Claim 2 is proved.

It can follow from Lemma 3.3 that

$$\partial_t \check{U}^{\nu}_{\xi} - \nu \partial_x^2 \check{U}^{\nu}_{\xi} = f(\psi^{\nu}_{\xi}) - f(u^{\nu}) - \int_{-\infty}^x h^{\nu}_{\xi}(y, t) dy \quad \forall x \in \mathbb{R}, \ t \geqslant T_2.$$

This and (3.48) yield that

$$\partial_t \check{U}^{\nu}_{\xi} - \nu \partial_x^2 \check{U}^{\nu}_{\xi} + a(u^{\nu}, \psi^{\nu}_{\xi}) \partial_x \check{U}^{\nu}_{\xi} > 0 \qquad \forall x \in \mathbb{R}, \ t \geqslant T_2, \tag{3.54}$$

where a is defined by (3.37). Then by (3.53), (3.54), and using the maximum principle, one can obtain

$$\check{U}^{\nu}_{\varepsilon}(x,t) \geqslant -\varepsilon/2 \qquad \forall x \in \mathbb{R}, \ t \geqslant T_2.$$
 (3.55)

This, together with (2.13) and (3.50), shows that

$$U_{l}^{\nu}(x,t) = \int_{-\infty}^{x} \left(u^{\nu} - u_{l}^{\nu}\right)(y,t)dy$$

$$= \int_{-\infty}^{x} \left(u^{\nu} - \psi_{\xi}^{\nu}\right)(y,t)dy + \int_{-\infty}^{x} \left(\psi_{\xi}^{\nu} - u_{l}^{\nu}\right)(y,t)dy$$

$$= \check{U}_{\xi}^{\nu}(x,t) - \int_{-\infty}^{x} \left(u_{l}^{\nu} - u_{r}^{\nu}\right)(y,t)\left(1 - g^{\nu}(y - \xi(t))\right)dy$$

$$\geq -\varepsilon/2 - 2(\overline{u}_{l} - \overline{u}_{r})\int_{-\infty}^{x} \left(1 - g^{\nu}(y - st + D)\right)dy$$

$$\geq -\varepsilon,$$

if $t \ge T_2$ and $x - st < -N_2$ with $N_2 > 0$ large enough.

Step 4. In the last step, we complete the proof of (3.39).

By Steps 1 and 3, for any $t > T_2$ and $x_1 < x_2 < st - N_3$, one has that

$$\left| \int_{x_1}^{x_2} (u^{\nu} - u_l^{\nu})(y, t) dy \right| \leqslant 2\varepsilon, \tag{3.56}$$

where $N_3 := \max\{N_1, N_2\}$. And by (1.4) and Lemma 2.4, there exists a positive number $M_3 > 0$ such that

$$\partial_x \left(u^{\nu} - u_l^{\nu} \right) \leqslant M_3 \quad \forall \ t > T_2, \ x \in \mathbb{R}. \tag{3.57}$$

Then (3.39) follows from the following Claim.

Claim 3. For any $t > T_2$, $x < st - N_3 - \frac{3\sqrt{\varepsilon}}{\sqrt{M_2}}$, it holds that

$$|u^{\nu}(x,t) - u_{I}^{\nu}(x,t)| \leqslant 3\sqrt{M_{3}\varepsilon}. \tag{3.58}$$

In fact, if there exist $t_0 > T_2$ and $x_0 < st_0 - N_3 - \frac{3\sqrt{\varepsilon}}{\sqrt{M_3}}$ such that

$$u^{\nu}(x_0, t_0) - u^{\nu}(x_0, t_0) < -3\sqrt{M_3\varepsilon},$$

then for any $x \in \left(x_0, x_0 + \frac{3\sqrt{\varepsilon}}{\sqrt{M_3}}\right)$, it holds that

$$(u^{\nu} - u_l^{\nu})(x, t_0) - (u^{\nu} - u_l^{\nu})(x_0, t_0) = \partial_x (u^{\nu} - u_l^{\nu})(\cdot, t_0)(x - x_0).$$

Due to (3.57), it follows from above that

$$(u^{\nu} - u_l^{\nu})(x, t_0) < -3\sqrt{M_3\varepsilon} + M_3(x - x_0).$$

Then integrating this inequality over $\left(x_0, x_0 + \frac{3\sqrt{\varepsilon}}{\sqrt{M_3}}\right)$ yields that

$$\int_{x_0}^{x_0 + \frac{3\sqrt{\varepsilon}}{\sqrt{M_3}}} (u^{\nu} - u_l^{\nu})(x, t_0) dx \leqslant -3\sqrt{M_3\varepsilon} \times \frac{3\sqrt{\varepsilon}}{\sqrt{M_3}} + \frac{M_3}{2} \times \frac{9\varepsilon}{M_3} = -\frac{9\varepsilon}{2} < -2\varepsilon,$$

which contradicts (3.56). For the other case that $u^{\nu}(x_0, t_0) - u^{\nu}_l(x_0, t_0) > 3\sqrt{M_3\varepsilon}$, it is also a contradiction by considering the interval $\left(x_0 - \frac{3\sqrt{\varepsilon}}{\sqrt{M_3}}, x_0\right)$ instead. So *Claim 3* holds true.

3.2.2. Anti-derivative variables.

In this part, we consider the equation of the anti-derivative of $u^{\nu} - \psi_{X^{\nu}}^{\nu}$. It turns out that the error term in the equation for the anti-derivative variable decays exponentially both in space and in time; see Proposition 3.5. And then the idea of Il'in and Oleĭnik [16] is applied to proving (2.19), i.e. we construct an auxiliary function $(\Theta(x))$ constructed below), and then use the maximal principle.

We first define the anti-derivative variable of $-h_{X^{\nu}}^{\nu}$ in (2.9) as

$$H^{\nu}(x,t) := -\int_{-\infty}^{x} h_{X^{\nu}(t)}^{\nu}(y,t) \, dy, \quad t \geqslant T_0, x \in \mathbb{R},. \tag{3.59}$$

Then due to (2.11), one has that

$$H^{\nu} = -\left(f(\psi_{X^{\nu}}^{\nu}) - f(u_{l}^{\nu})\right)g_{X^{\nu}}^{\nu} - \left(f(\psi_{X^{\nu}}^{\nu}) - f(u_{r}^{\nu})\right)\left(1 - g_{X^{\nu}}^{\nu}\right)$$

$$+ 2\nu(u_{l}^{\nu} - u_{r}^{\nu})(g_{X^{\nu}}^{\nu})' - \int_{-\infty}^{x} (f(u_{l}^{\nu}) - f(u_{r}^{\nu}))(y, t)(g_{X^{\nu}}^{\nu})'(y)dy$$

$$+ (X^{\nu})' \int_{-\infty}^{x} (u_{l}^{\nu} - u_{r}^{\nu})(y, t)(g_{X^{\nu}}^{\nu})'(y)dy$$

$$- \nu \int_{-\infty}^{x} (u_{l}^{\nu} - u_{r}^{\nu})(y, t)(g_{X^{\nu}}^{\nu})''(y)dy.$$
(3.60)

On the other hand, by Lemma 3.2, one can define the anti-derivative variable of $u^{\nu} - \psi^{\nu}_{X^{\nu}}$ as

$$U^{\nu}(x,t) := \check{U}_{X^{\nu}}^{\nu}(x,t) = \int_{-\infty}^{x} (u^{\nu} - \psi_{X^{\nu}}^{\nu})(y,t)dy, \quad t \geqslant 0, x \in \mathbb{R}.$$
 (3.61)

For convenience, in the following part of this paper we define

$$\overline{a}(x,t) := a(u^{\nu}, \psi^{\nu}_{X^{\nu}})(x,t). \tag{3.62}$$

Proposition 3.5. The functions $H^{\nu}(x,t)$ and $\overline{a}(x,t)$ are smooth in $\mathbb{R} \times [T_0, +\infty)$, and $U^{\nu}(x,t)$ solves the equation

$$\partial_t U^{\nu} - \nu \partial_x^2 U^{\nu} + \overline{a} \ \partial_x U^{\nu} = H^{\nu}, \quad x \in \mathbb{R}, \ t \geqslant T_0, \tag{3.63}$$

where all the derivatives of U^{ν} appearing in (3.63) are continuous in $\mathbb{R} \times [T_0, +\infty)$. Moreover, $H^{\nu}(x,t)$ satisfies

$$|H^{\nu}(x,t)| \leqslant Ce^{-\alpha t}e^{-\beta|x-X^{\nu}(t)|} \quad \forall x \in \mathbb{R}, \ t \geqslant T_0, \tag{3.64}$$

and $U^{\nu}(x,t)$ satisfies

$$|U^{\nu}(x,t)| \leqslant C(t)e^{-\beta|x-X^{\nu}(t)|} \quad \forall x \in \mathbb{R}, \ t \geqslant T_0, \tag{3.65}$$

where C > 0 is a constant, independent of time t, and C(t) > 0 is bounded on any compact subset of $[T_0, +\infty)$.

Proof. The smoothness of $H^{\nu}(x,t)$ and $\overline{a}(x,t)$ can be derived easily from Lemma 2.4 and the smoothness of u^{ν} , u^{ν}_{l} , u^{ν}_{r} and $\psi^{\nu}_{X^{\nu}}$. By Lemma 3.3, $U^{\nu} = \check{U}^{\nu}_{X^{\nu}}$ solves (3.63) and all the derivatives of U^{ν} appearing in (3.63) are continuous in $\mathbb{R} \times [T_0, +\infty)$.

Now we prove (3.64). Note that there exists a unique $x_0 \in \mathbb{R}$ such that, if $x < x_0$, $(g^{\nu})''(x) < 0$, and if $x > x_0$, $(g^{\nu})''(x) > 0$. Then for $x < X^{\nu}(t) + x_0$, it follows from (3.60) and Lemma 2.4 that

$$H^{\nu}(x,t) = -\left(f(\psi_{X^{\nu}}^{\nu}) - f(u_{l}^{\nu})\right) - \left(f(\overline{u}_{l}) - f(\overline{u}_{r}) + O\left(e^{-\alpha t}\right)\right) \left(1 - g_{X^{\nu}}^{\nu}\right)$$

$$+ 2\nu \left(\overline{u}_{l} - \overline{u}_{r} + O\left(e^{-\alpha t}\right)\right) \left(g_{X^{\nu}}^{\nu}\right)' - \int_{-\infty}^{x} \left(f(\overline{u}_{l}) - f(\overline{u}_{r}) + O\left(e^{-\alpha t}\right)\right) \left(g_{X^{\nu}}^{\nu}\right)'(y) dy$$

$$+ \left(s + O\left(e^{-\alpha t}\right)\right) \int_{-\infty}^{x} \left(\overline{u}_{l} - \overline{u}_{r} + O\left(e^{-\alpha t}\right)\right) \left(g_{X^{\nu}}^{\nu}\right)'(y) dy$$

$$- \nu \int_{-\infty}^{x} \left(\overline{u}_{l} - \overline{u}_{r} + O\left(e^{-\alpha t}\right)\right) \left(g_{X^{\nu}}^{\nu}\right)''(y) dy.$$

If $x < X^{\nu}(t) + x_0$, it holds that $\int_{-\infty}^{x} |(g_{X^{\nu}}^{\nu})''| dy = -\int_{-\infty}^{x} (g_{X^{\nu}}^{\nu})'' dy = -(g_{X^{\nu}}^{\nu})'(x)$, and $0 < 1 - g_{Y^{\nu}}^{\nu}(x) + |(g_{Y^{\nu}}^{\nu})'(x)| \le Ce^{\beta(x-X^{\nu}(t))}$, then

$$H^{\nu}(x,t) = -\left(f(\psi_{X^{\nu}}^{\nu}) - f(u_{l}^{\nu})\right) - \left(f(\overline{u}_{l}) - f(\overline{u}_{r})\right) \left(1 - g_{X^{\nu}}^{\nu}\right) + 2\nu(\overline{u}_{l} - \overline{u}_{r})\left(g_{X^{\nu}}^{\nu}\right)' + \left(f(\overline{u}_{l}) - f(\overline{u}_{r})\right) \left(1 - g_{X^{\nu}}^{\nu}\right) - s(\overline{u}_{l} - \overline{u}_{r})\left(1 - g_{X^{\nu}}^{\nu}\right) - \nu(\overline{u}_{l} - \overline{u}_{r})(g_{X^{\nu}}^{\nu})' + O\left(e^{-\alpha t}e^{\beta(x - X^{\nu}(t))}\right) \\ = -\left(f(\psi_{X^{\nu}}^{\nu}) - f(u_{l}^{\nu})\right) + \left(f(\phi_{X^{\nu}}^{\nu}) - f(\overline{u}_{l})\right) \\ = -a(\psi_{X^{\nu}}^{\nu}, u_{l}^{\nu})\left(\psi_{X^{\nu}}^{\nu} - u_{l}^{\nu}\right) + a(\phi_{X^{\nu}}^{\nu}, \overline{u}_{l})\left(\phi_{X^{\nu}}^{\nu} - \overline{u}_{l}\right) \\ = a(\psi_{X^{\nu}}^{\nu}, u_{l}^{\nu})\left(u_{l}^{\nu} - u_{r}^{\nu}\right)\left(1 - g_{X^{\nu}}^{\nu}\right) - a(\phi_{X^{\nu}}^{\nu}, \overline{u}_{l})(\overline{u}_{l} - \overline{u}_{r})\left(1 - g_{X^{\nu}}^{\nu}\right) \\ = (\overline{u}_{l} - \overline{u}_{r})\left(1 - g_{X^{\nu}}^{\nu}\right)\left(a(\psi_{X^{\nu}}^{\nu}, u_{l}^{\nu}) - a(\phi_{X^{\nu}}^{\nu}, \overline{u}_{l})\right) + O\left(e^{-\alpha t}e^{\beta(x - X^{\nu}(t))}\right).$$

And it is easy to verify that

$$a(\psi_{X^{\nu}}^{\nu}, u_l^{\nu}) - a(\phi_{X^{\nu}}^{\nu}, \overline{u}_l) = O\left(e^{-\alpha t}\right),\,$$

which implies that if $x < X^{\nu}(t) + x_0$, $H^{\nu}(x,t) = O\left(e^{-\alpha t}e^{\beta(x-X^{\nu}(t))}\right)$. On the other hand, if $x > X^{\nu}(t) + x_0$, $\int_x^{+\infty} |(g_{X^{\nu}}^{\nu})''| dy = \int_x^{+\infty} (g_{X^{\nu}}^{\nu})'' dy = -(g_{X^{\nu}}^{\nu})'(x)$, and $0 < g_{X^{\nu}}^{\nu}(x) + |(g_{X^{\nu}}^{\nu})'(x)| \le Ce^{-\beta(x-X^{\nu}(t))}$. It follows from (2.15) that for any $t > T_0$ and

 $x \in \mathbb{R}$.

$$H^{\nu}(x,t) = -\left(f(\psi_{X^{\nu}}^{\nu}) - f(u_{l}^{\nu})\right) g_{X^{\nu}}^{\nu} - \left(f(\psi_{X^{\nu}}^{\nu}) - f(u_{r}^{\nu})\right) \left(1 - g_{X^{\nu}}^{\nu}\right)$$

$$+ 2\nu(u_{l}^{\nu} - u_{r}^{\nu}) \left(g_{X^{\nu}}^{\nu}\right)' + \int_{x}^{+\infty} (f(u_{l}^{\nu}) - f(u_{r}^{\nu}))(y,t)(g_{X^{\nu}}^{\nu})'(y)dy$$

$$- (X^{\nu})'(t) \int_{x}^{+\infty} (u_{l}^{\nu} - u_{r}^{\nu})(y,t) \left(g_{X^{\nu}}^{\nu}\right)'(y)dy$$

$$+ \nu \int_{x}^{+\infty} (u_{l}^{\nu} - u_{r}^{\nu})(y,t) \left(g_{X^{\nu}}^{\nu}\right)''(y)dy.$$

$$(3.66)$$

Then by similar arguments as in the case that $x < X^{\nu}(t) + x_0$, one can prove that if $x > X^{\nu}(t) + x_0$, $H^{\nu}(x,t) = O\left(e^{-\alpha t}e^{-\beta(x-X^{\nu}(t))}\right)$. Hence, one can get (3.64).

Now we will prove (3.65). Similar to the proof of (3.5), one can apply (2.15) and (2.17) to obtain that

$$\int_{-\infty}^{+\infty} \left(u^{\nu}(x,t) - \psi^{\nu}_{X^{\nu}(t)}(x,t) \right) dx = 0 \quad \forall t \geqslant T_0.$$

Hence, for any $x \in \mathbb{R}$ and t > 0, one has that

$$U^{\nu}(x,t) = \int_{-\infty}^{x} \left(u^{\nu} - \psi_{X^{\nu}}^{\nu}\right)(y,t)dy = -\int_{x}^{+\infty} \left(u^{\nu} - \psi_{X^{\nu}}^{\nu}\right)(y,t)dy. \tag{3.67}$$

Lemma 3.1 implies that $|X^{\nu}(t)| \leq C + |s|t$. Then by Lemma 3.2, one has that

$$|u^{\nu}(x,t) - \psi^{\nu}_{X^{\nu}}(x,t)| \leqslant C(t)e^{\beta|X^{\nu}(t)|}e^{-\beta|x-X^{\nu}(t)|} \leqslant C_2(t)e^{-\beta|x-X^{\nu}(t)|}$$

which, together with (3.67), yields (3.65).

Denote the positive constant $\varepsilon_1 := \min\left\{\frac{f'(\overline{u}_l) - s}{2}, -\frac{f'(\overline{u}_r) - s}{2}\right\} > 0.$

Lemma 3.6. There exist positive constants $T_3 > T_2$ and N_0 , independent of time, such that

$$\overline{a}(x,t) - (X^{\nu})'(t) > \varepsilon_1 > 0, \qquad x - X^{\nu}(t) < -N_0, \ t > T_3,$$
 (3.68)

$$\overline{a}(x,t) - (X^{\nu})'(t) < -\varepsilon_1 < 0, \quad x - X^{\nu}(t) > N_0, \ t > T_3.$$
 (3.69)

Proof. Here we prove (3.68) only, since (3.69) can be proved similarly.

By (3.37), $\overline{a}(x,t) = \int_0^1 f'(\psi_{X^{\nu}}^{\nu} + \rho(u^{\nu} - \psi_{X^{\nu}}^{\nu})) d\rho$, where

$$\begin{aligned} &|\psi_{X^{\nu}}^{\nu} + \rho(u^{\nu} - \psi_{X^{\nu}}^{\nu}) - \overline{u}_{l}| \\ &= |u_{l}^{\nu} g_{X^{\nu}}^{\nu} + u_{r}^{\nu} (1 - g_{X^{\nu}}^{\nu}) + \rho(u^{\nu} - u_{l}^{\nu}) + \rho(u_{l}^{\nu} - u_{r}^{\nu}) (1 - g_{X^{\nu}}^{\nu}) - \overline{u}_{l}| \\ &= |(u_{l}^{\nu} - \overline{u}_{l}) - (1 - \rho)(u_{l}^{\nu} - u_{r}^{\nu}) (1 - g_{X^{\nu}}^{\nu}) + \rho(u^{\nu} - u_{l}^{\nu})| \\ &\leq |u_{l}^{\nu} - \overline{u}_{l}| + 2(\overline{u}_{l} - \overline{u}_{r}) (1 - g_{X^{\nu}}^{\nu}) + |u^{\nu} - u_{l}^{\nu}|. \end{aligned}$$

Lemma 3.1 shows that $|X^{\nu}(t) - st| \leq C$. Then by combining Lemmas 2.1, 2.4 and Proposition 3.4, one can get that for any $\varepsilon > 0$, there exist $T(\varepsilon) > T_2$ and $N(\varepsilon) > 0$ such that

$$|\psi_{X^{\nu}}^{\nu} + \rho(u^{\nu} - \psi_{X^{\nu}}^{\nu}) - \overline{u}_l| < \varepsilon \qquad \forall t > T(\varepsilon), \ x - X^{\nu}(t) < -N(\varepsilon),$$

and hence,

$$|f'(\psi_{X^{\nu}}^{\nu} + \rho(u^{\nu} - \psi_{X^{\nu}}^{\nu})) - f'(\overline{u}_l)| \leqslant C\varepsilon \qquad \forall t > T(\varepsilon), \ x - X^{\nu}(t) < -N(\varepsilon).$$

Then it follows from Lemma 3.1 that

$$\overline{a} - (X^{\nu})' > f'(\overline{u}_l) - C\varepsilon - s + (s - (X^{\nu})'(t))
\geqslant f'(\overline{u}_l) - C\varepsilon - s - Ce^{-\alpha t}
\geqslant \frac{f'(\overline{u}_l) - s}{2} \qquad \forall t > T_3, \ x - X^{\nu}(t) < -N_0,$$

provided that ε is small enough, and $N_0 > N(\varepsilon)$ and $T_3 > T(\varepsilon)$ are large enough. \square

Define the linear operator

$$L := \partial_t - \nu \partial_x^2 + \overline{a}(x, t) \partial_x. \tag{3.70}$$

Proposition 3.5 shows that $LU^{\nu} = H^{\nu}$ on $\{t \geq T_0\}$. For the constant N_0 given in Lemma 3.6, we define the auxiliary functions as [16],

$$\theta(x) := \begin{cases} \cosh(\gamma x), & |x| \leq N_0, \\ \theta_1(x), & N_0 < |x| \leq N_0 + 1, \\ \theta_2(x), & |x| > N_0 + 1, \end{cases}$$

$$\Theta(x) := e^{-\delta\theta(x)},$$
(3.71)

where γ and δ are two positive constants to be determined, and

$$\theta_1(x) := -\frac{\gamma^2}{6} \cosh(\gamma N_0) (|x| - N_0)^3 + \frac{\gamma^2}{2} \cosh(\gamma N_0) (|x| - N_0)^2 + \gamma \sinh(\gamma N_0) (|x| - N_0) + \cosh(\gamma N_0),$$

$$\theta_2(x) := \theta_1'(N_0 + 1) (|x| - N_0 - 1) + \theta_1(N_0 + 1),$$

thus $\theta(x)$ is a convex and C^2 function on \mathbb{R} .

Lemma 3.7. There exist positive constants γ, δ and μ , independent of time t, such that the auxiliary function Θ defined above satisfies that

$$L(\Theta(x - X^{\nu}(t))) \geqslant 2\mu\Theta(x - X^{\nu}(t)) \qquad \forall x \in \mathbb{R}, \ t > T_3.$$

Proof. We define $\zeta := x - X^{\nu}(t)$ for simplicity. By (3.70), it holds that

$$L(\Theta(\zeta)) = e^{-\delta\theta(\zeta)} \left[\delta(X^{\nu})'(t)\theta'(\zeta) - \delta^{2}\nu(\theta'(\zeta))^{2} + \delta\nu\theta''(\zeta) - \delta\overline{a} \theta'(\zeta) \right]$$
$$= \delta\Theta(\zeta) \left[\nu\theta''(\zeta) - (\overline{a}(x,t) - (X^{\nu})'(t)) \theta'(\zeta) - \delta\nu(\theta'(\zeta))^{2} \right]$$

There are three cases to be considered.

(1) If
$$|\zeta| < N_0$$
, $\theta(\zeta) = \cosh(\gamma \zeta)$. Therefore,

$$\nu \theta''(\zeta) - (\overline{a}(x,t) - (X^{\nu})'(t)) \theta'(\zeta) - \delta \nu (\theta'(\zeta))^2$$

$$= \nu \gamma^2 \cosh(\gamma \zeta) - (\overline{a} - (X^{\nu})') \gamma \sinh(\gamma \zeta) - \delta \nu \gamma^2 (\sinh(\gamma \zeta))^2$$

$$= \gamma \cosh(\gamma \zeta) \Big[\nu \gamma (1 - \delta \sinh(\gamma \zeta) \tanh(\gamma \zeta)) - (\overline{a} - (X^{\nu})'(t)) \tanh(\gamma \zeta) \Big].$$

Since $\overline{a} - (X^{\nu})'$ is bounded, one can first choose $\gamma > 0$ large enough such that

$$|\overline{a} - (X^{\nu})'| < \frac{\nu \gamma}{4} \qquad \forall x \in \mathbb{R}, t > T_0.$$

For $|\zeta| < N_0$, $|\sinh(\gamma \zeta)| < e^{\gamma N_0}$, then one can choose $\delta = \delta(\gamma, N_0) > 0$ small enough such that

$$1 - \delta e^{\gamma N_0} \geqslant \frac{1}{2}.$$

Hence, by $|\tanh(\gamma\zeta)| \leq 1$ and $\cosh(\gamma\zeta) \geq 1$, it holds that for $|\zeta| < N_0$ and $t > T_3$,

$$L(\Theta(\zeta)) \geqslant \delta\Theta(\zeta) \cdot \gamma \cosh(\gamma \zeta) \cdot \frac{\nu \gamma}{4} \geqslant \frac{\delta \nu \gamma^2}{4} \Theta(\zeta).$$

(2) If $\zeta > N_0$, it holds that $0 < k_1 \le \theta'(\zeta) \le k_2$, where $k_1 = \theta'_1(N_0) = \gamma \sinh(\gamma N_0)$ and $k_2 = \theta'_1(N_0 + 1) = \frac{\gamma^2}{2} \cosh(\gamma N_0) + \gamma \sinh(\gamma N_0)$. It follows from the fact $\theta'' \ge 0$ and Lemma 3.6 that

$$\nu\theta''(\zeta) - (\overline{a} - (X^{\nu})'(t)) \theta'(\zeta) - \delta\nu(\theta'(\zeta))^{2}$$

$$\geq - (\overline{a} - (X^{\nu})') \theta'(\zeta) - \delta\nu(\theta'(\zeta))^{2}$$

$$\geq \theta'(\zeta) (\varepsilon_{1} - \delta\nu\theta'(\zeta))$$

One can choose $\delta = \delta(\gamma, N_0, \varepsilon_1) > 0$ small enough such that for $\zeta > N_0$,

$$\delta \nu \theta'(\zeta) \leqslant \delta \nu k_2 \leqslant \frac{\varepsilon_1}{2}.$$

Hence,

$$L(\Theta(\zeta)) \geqslant \delta\Theta(\zeta) \cdot k_1 \cdot \frac{\varepsilon_1}{2} \geqslant \frac{\delta k_1 \varepsilon_1}{2} \Theta(\zeta).$$
 (3.72)

(3) For $\zeta < -N_0$, it holds that $-k_2 \leqslant \theta'(\zeta) \leqslant -k_1 < 0$, then one can similarly prove that (3.72) holds true.

Collecting (1), (2) and (3), one can prove the lemma by choosing γ sufficiently large, δ sufficiently small, and $\mu = \min \left\{ \frac{\delta \nu \gamma^2}{8}, \frac{\delta k_1 \varepsilon_1}{4} \right\}$.

3.2.3. Proof of Proposition 2.7.

Set

$$Z(x,t) := M_4 e^{-\mu t} \Theta(x - X^{\nu}(t)) \pm U^{\nu}(x,t), \quad x \in \mathbb{R}, t \ge 0,$$

where $M_4 > 0$ is a constant to be determined, and μ is the constant in Lemma 3.7, which can be actually chosen small enough such that $0 < \mu \leq \min\{1, \alpha\}$. Due to (3.64) and Lemma 3.7, it holds that

$$LZ = -\mu M_4 e^{-\mu t} \Theta(x - X^{\nu}(t)) + M_4 e^{-\mu t} L\left(\Theta(x - X^{\nu}(t))\right) \pm H^{\nu}$$

$$\geq (-\mu + 2\mu) M_4 e^{-\mu t} \Theta(x - X^{\nu}(t)) - C e^{-\alpha t} e^{-\beta |x - X^{\nu}(t)|}$$

$$\geq e^{-\mu t} \left(\mu M_4 e^{-\delta \theta(x - X^{\nu}(t))} - C e^{-\beta |x - X^{\nu}(t)|}\right).$$
(3.73)

By (3.65), one has

$$Z(x, T_3) \geqslant M_4 e^{-\mu T_3} e^{-\delta \theta (x - X^{\nu}(T_3))} - C(T_3) e^{-\beta |x - X^{\nu}(T_3)|}$$

We consider two cases:

(1) If x satisfies $|x - X^{\nu}(T_3)| \leq N_0 + 1$, then

$$M_4 e^{-\mu T_3} e^{-\delta \theta(x-X^{\nu}(T_3))} - C(T_3) e^{-\beta|x-X^{\nu}(T_3)|} \geqslant M_4 e^{-\mu T_3} e^{-\delta \theta(N_0+1)} - C(T_3).$$

Therefore, choosing $M_4 > C(T_3)e^{\mu T_3}e^{\delta\theta(N_0+1)}$, one gets that $Z(x,T_3) > 0$.

(2) If x satisfies $|x - X^{\nu}(T_3)| > N_0 + 1$, then $\theta = \theta_2$ is linear. Then one has that $M_4 e^{-\mu T_3} e^{-\delta \theta (x - X^{\nu}(T_3))} - C(T_3) e^{-\beta |x - X^{\nu}(T_3)|}$

$$\geqslant M_4 e^{-\mu T_3} e^{\delta(N_0+1)\theta_1'(N_0+1) - \delta\theta_1(N_0+1)} e^{-\delta\theta_1'(N_0+1)|x-X^{\nu}(T_3)|} - C(T_3) e^{-\beta|x-X^{\nu}(T_3)|}$$

Then by choosing $\delta > 0$ small enough such that $\delta \theta'_1(N_0 + 1) \leq \beta$, and $M_4 > 0$ large enough such that

$$M_4 > C(T_3)e^{\mu T_3}e^{\delta(N_0+1)\theta_1'(N_0+1)-\delta\theta_1(N_0+1)}$$

one can also obtain that $Z(x, T_3) > 0$.

Similarly, for any $t > T_3$, one can also consider the two cases $|x - X^{\nu}(t)| \leq N_0 + 1$ and $|x - X^{\nu}(t)| > N_0 + 1$ in (3.73) to prove that there exist $\delta > 0$ small enough and $M_4 > 0$ large enough such that

$$LZ > 0 \qquad \forall x \in \mathbb{R}, t > T_3.$$

Therefore, the maximum principle implies that $Z(x,t) \ge 0$ for any $x \in \mathbb{R}, t \ge T_3$, which yields that

$$|U^{\nu}(x,t)| \leq M_4 e^{-\mu t} \Theta(x - X^{\nu}(t)) \leq M_4 e^{-\mu t} \qquad \forall x \in \mathbb{R}, t \geq T_3.$$

Hence, by the definition (3.61) of U^{ν} , one has that for any $x_1 < x_2$ and $t \ge T_3$,

$$\left| \int_{x_1}^{x_2} \left(u^{\nu}(y,t) - \psi_{X^{\nu}}^{\nu}(y,t) \right) dy \right| = \left| U^{\nu}(x_2,t) - U^{\nu}(x_1,t) \right| \le 2M_4 e^{-\mu t}. \tag{3.74}$$

By (1.4) and Lemmas 2.1 and 2.4, there exists a constant $M_5 > 0$, independent of time t, such that for any $x \in \mathbb{R}$ and $t \ge T_3$,

$$\partial_x (u^{\nu} - \psi_{X^{\nu}}^{\nu}) = \partial_x (u^{\nu} - u_l^{\nu}) g_{X^{\nu}}^{\nu} + \partial_x (u^{\nu} - u_r^{\nu}) (1 - g_{X^{\nu}}^{\nu}) - (u_l^{\nu} - u_r^{\nu}) (g_{X^{\nu}}^{\nu})' \leqslant M_5. \quad (3.75)$$

It then follows from (3.74) and (3.75) that the following claim holds true.

 $Claim\ 5.$

$$|u^{\nu}(x,t) - \psi^{\nu}_{X^{\nu}}(x,t)| \le 3\sqrt{M_4 M_5} e^{-\frac{\mu}{2}t} \qquad \forall x \in \mathbb{R}, t \ge T_3.$$

Indeed, if there exists (x_0, t_0) with $x_0 \in \mathbb{R}$ and $t_0 \ge T_3$, such that

$$u^{\nu}(x_0, t_0) - \psi^{\nu}_{X^{\nu}}(x_0, t_0) < -3\sqrt{M_4M_5}e^{-\frac{\mu}{2}t_0}.$$

Then for any $x \in (x_0, x_1)$, where $x_1 := x_0 + 3\sqrt{\frac{M_4}{M_5}}e^{-\frac{\mu}{2}t_0}$, (3.75) yields that

$$(u^{\nu}(x,t_0) - \psi^{\nu}_{X^{\nu}}(x,t_0)) - (u^{\nu}(x_0,t_0) - \psi^{\nu}_{X^{\nu}}(x_0,t_0)) \leqslant M_5(x-x_0).$$

Then

$$\int_{x_0}^{x_1} \left(u^{\nu}(x, t_0) - \psi_{X^{\nu}}^{\nu}(x, t_0) \right) dx$$

$$\leqslant \left(u^{\nu}(x_0, t_0) - \psi_{X^{\nu}}^{\nu}(x_0, t_0) \right) (x_1 - x_0) + \frac{M_5}{2} (x_1 - x_0)^2$$

$$\leqslant -3\sqrt{M_4 M_5} e^{-\frac{\mu}{2} t_0} \cdot 3\sqrt{\frac{M_4}{M_5}} e^{-\frac{\mu}{2} t_0} + \frac{M_5}{2} \cdot 9 \frac{M_4}{M_5} e^{-\mu t_0}$$

$$= -\frac{9}{2} M_4 e^{-\mu t_0} < -2M_4 e^{-\mu t_0},$$

which contradicts (3.74). In the other case for $u^{\nu}(x_0, t_0) - \psi^{\nu}_{X^{\nu}}(x_0, t_0) > 3\sqrt{M_4 M_5} e^{-\frac{\mu}{2}t_0}$ at some point (x_0, t_0) , a contradiction can be obtained similarly by considering the interval $\left(x_0 - 3\sqrt{\frac{M_4}{M_5}}e^{-\frac{\mu}{2}t_0}, x_0\right)$ instead.

Therefore, the claim above is proved. This, together with the fact that u^{ν} and $\psi_{X^{\nu}}^{\nu}$ are both bounded, yields (2.19).

3.3. More results for Burgers' equation.

In this section, we prove the result (1) in Theorem 1.3 and Proposition 2.8 for the Burgers' equation (1.1), where $f(u) = u^2/2$ and $w_{0l} \equiv w_{0r}$ has the same period p > 0.

First, under the assumptions of Theorem 1.3, one can use the Galilean transformation to verify that the periodic functions w_l^{ν} and w_r^{ν} defined in (3.11) satisfy

$$w_l^{\nu}(x,t) = w_r^{\nu}\left(x - (\overline{u}_l - \overline{u}_r)t, t\right), \qquad x \in \mathbb{R}, t \geqslant 0, \tag{3.76}$$

Therefore, since both w_l^{ν} and w_r^{ν} are of average zero, it holds that for any t>0,

$$\int_{0}^{t} \int_{0}^{p} \left\{ \left[f(u_{l}^{\nu}) - f(\overline{u}_{l}) \right] - \left[f(u_{r}^{\nu}) - f(\overline{u}_{r}) \right] \right\} dx d\tau
= \int_{0}^{t} \int_{0}^{p} \frac{1}{2} \left\{ \left[2\overline{u}_{l} + w_{l}^{\nu}(x,\tau) \right] w_{l}^{\nu}(x,\tau) - \left[2\overline{u}_{r} + w_{r}^{\nu}(x,\tau) \right] w_{r}^{\nu}(x,\tau) \right\} dx d\tau
= \int_{0}^{t} \int_{0}^{p} \frac{1}{2} \left[(w_{l}^{\nu})^{2}(x,\tau) - (w_{r}^{\nu})^{2}(x,\tau) \right] dx d\tau
= \int_{0}^{t} \int_{0}^{p} \frac{1}{2} (w_{r}^{\nu})^{2} \left(x - (\overline{u}_{l} - \overline{u}_{r})t, \tau \right) dx d\tau - \int_{0}^{t} \int_{0}^{p} \frac{1}{2} (w_{r}^{\nu})^{2}(x,\tau) dx d\tau
= 0.$$
(3.77)

Thus, letting $t \to +\infty$ in (3.77) shows that $X_{\infty,2}^{\nu}$ defined in (1.11) is identically zero.

Under the assumptions of Proposition 2.8, it holds that $u_l^{\nu}(x,t) \ge u_r^{\nu}(x,t)$ for all $x \in \mathbb{R}$ and t > 0, thus

$$\int_{\mathbb{R}} (u_l^{\nu}(x,t) - u_r^{\nu}(x,t))(g_{\xi}^{\nu})'(x)dx = \int_0^p (u_l^{\nu}(x,t) - u_r^{\nu}(x,t)) \sum_{k \in \mathbb{Z}} (g_{\xi}^{\nu})'(x+kp)dx
\leq -C \int_0^p (u_l^{\nu}(x,t) - u_r^{\nu}(x,t)) \sum_{k \in \mathbb{Z}} e^{-\beta(x+kp)} dx
\leq -C e^{-\beta p} \int_0^p (u_l^{\nu}(x,t) - u_r^{\nu}(x,t)) dx
= -C e^{-\beta p} p(\overline{u}_l - \overline{u}_r) < 0.$$

Then the number M in (3.2) can be chosen to be zero, such that the denominator of $F^{\nu}(\xi,t)$ is non-zero for any $t \geq 0$. Moreover, since M=0 and the initial data given in Proposition 2.8 satisfies $\int_{\mathbb{R}} (u_0(x) - \psi_0^{\nu}(x)) dx = 0$, the unique number \hat{X}_0^{ν} satisfying (3.5) is zero. Hence, one can get that the curve \tilde{X}^{ν} defined in (3.8) actually solves

$$\begin{cases} \left(\tilde{X}^{\nu}\right)'(t) = F^{\nu}\left(\tilde{X}^{\nu}, t\right), & t > 0, \\ \tilde{X}^{\nu}(0) = 0. \end{cases}$$
(3.78)

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Due to (3.76), if $(\overline{u}_l - \overline{u}_r)t_k = kp$ for any $k \ge 0$, one has $w_l^{\nu}(x, t_k) \equiv w_r^{\nu}(x, t_k)$. Thus the term J^N defined in (3.12) and the limit J satisfy that

$$J^{N}(y,t_{k}) \equiv 0 \quad \Rightarrow \quad J(y,t_{k}) = \lim_{N \to +\infty} J^{N}(y,t_{k}) \equiv 0. \tag{3.79}$$

Then taking (3.77), $M = \hat{X}_0^{\nu} = 0$, and (3.79) into (3.17) yields that $\tilde{X}^{\nu}(t_k) = st_k$, and thus (2.22) holds true.

It remains to prove (2.21). In [14], Hopf introduced the well known Hopf transformation to obtain an explicit formula for the solution to (1.1) with any initial data $u_0 \in L^{\infty}$, which is given by:

$$u^{\nu}(x,t) = \frac{\int_{\mathbb{R}} \frac{x-y}{t} \exp\left\{-\frac{(x-y)^2}{4\nu t} - \frac{1}{2\nu} \int_0^y u_0(\eta) d\eta\right\} dy}{\int_{\mathbb{R}} \exp\left\{-\frac{(x-y)^2}{4\nu t} - \frac{1}{2\nu} \int_0^y u_0(\eta) d\eta\right\} dy}, \qquad x \in \mathbb{R}, t > 0.$$
 (3.80)

Since u_0 is bounded, then integration by parts on the numerator of (3.80) yields that

$$u^{\nu}(x,t) = \frac{\int_{\mathbb{R}} u_0(y) \exp\left\{-\frac{(x-y)^2}{4\nu t} - \frac{1}{2\nu} \int_0^y u_0(\eta) d\eta\right\} dy}{\int_{\mathbb{R}} \exp\left\{-\frac{(x-y)^2}{4\nu t} - \frac{1}{2\nu} \int_0^y u_0(\eta) d\eta\right\} dy}, \qquad x \in \mathbb{R}, t > 0.$$
 (3.81)

Without loss of generality (the viscous shock profile is unique up to a shift), the viscous shock ϕ^{ν} connecting the end states \overline{u}_l at $x = -\infty$ and \overline{u}_r at $x = +\infty$ to the Burgers' equation can be given by the explicit formula

$$\phi^{\nu}(x) = \frac{\overline{u}_l + \overline{u}_r}{2} - \frac{\overline{u}_l - \overline{u}_r}{2} \tanh\left(\frac{\overline{u}_l - \overline{u}_r}{4\nu}x\right).$$

Set $\lambda := \frac{\overline{u}_l - \overline{u}_r}{4\nu}$ for convenience. Then the associated g^{ν} defined in (2.3) is given by

$$g^{\nu}(x) = \frac{1 - \tanh(\lambda x)}{2} = \frac{e^{-\lambda x}}{e^{\lambda x} + e^{-\lambda x}},$$
(3.82)

satisfying

$$\phi^{\nu}(x) = \overline{u}_l g^{\nu}(x) + \overline{u}_r (1 - g^{\nu}(x)). \tag{3.83}$$

And one also has that

$$\int_{0}^{x} g^{\nu}(y) \, dy = \frac{1}{2} \int_{0}^{x} \left(1 - \tanh(\lambda y) \right) dy = \frac{1}{2\lambda} \ln\left(\frac{e^{\lambda x}}{e^{\lambda x} + e^{-\lambda x}}\right) + \frac{1}{2\lambda} \ln 2$$

$$= \frac{1}{2\lambda} \ln\left(1 - g^{\nu}(x)\right) + \frac{1}{2\lambda} \ln 2.$$
(3.84)

Similarly,

$$\int_0^x (1 - g^{\nu}(y)) \, dy = -\frac{1}{2\lambda} \ln g^{\nu}(x) - \frac{1}{2\lambda} \ln 2. \tag{3.85}$$

For the initial data $u_0(x) = \phi^{\nu}(x) + w_0(x)$ with $\int_0^p w_0(x) dx = 0$, it follows from (3.81) and (3.83) that

$$u^{\nu}(x,t) = \frac{P_l(x,t) + P_r(x,t)}{Q_l(x,t) + Q_r(x,t)},$$
(3.86)

where

$$P_{l}(x,t) := 2 \int_{\mathbb{R}} (\overline{u}_{l} + w_{0}(y)) g^{\nu}(y) \exp\left\{-\frac{(x-y)^{2}}{4\nu t} - \frac{1}{2\nu} \int_{0}^{y} u_{0}(\eta) d\eta\right\} dy,$$

$$P_{r}(x,t) := 2 \int_{\mathbb{R}} (\overline{u}_{r} + w_{0}(y)) (1 - g^{\nu}(y)) \exp\left\{-\frac{(x-y)^{2}}{4\nu t} - \frac{1}{2\nu} \int_{0}^{y} u_{0}(\eta) d\eta\right\} dy,$$

$$Q_{l}(x,t) := 2 \int_{\mathbb{R}} g^{\nu}(y) \exp\left\{-\frac{(x-y)^{2}}{4\nu t} - \frac{1}{2\nu} \int_{0}^{y} u_{0}(\eta) d\eta\right\} dy,$$

$$Q_{r}(x,t) := 2 \int_{\mathbb{R}} (1 - g^{\nu}(y)) \exp\left\{-\frac{(x-y)^{2}}{4\nu t} - \frac{1}{2\nu} \int_{0}^{y} u_{0}(\eta) d\eta\right\} dy.$$

It can follow from (3.85), $\lambda = \frac{\overline{u}_l - \overline{u}_r}{4\nu}$, and $u_0 = \overline{u}_l g^{\nu} + \overline{u}_r (1 - g^{\nu}) + w_0 = \overline{u}_l + w_0 - (\overline{u}_l - \overline{u}_r)(1 - g^{\nu})$ that

$$g^{\nu}(y) \exp\left\{-\frac{1}{2\nu} \int_{0}^{y} u_{0}(\eta) d\eta\right\}$$

$$= g^{\nu}(y) \exp\left\{2\lambda \int_{0}^{y} (1 - g^{\nu}(\eta)) d\eta\right\} \exp\left\{-\frac{1}{2\nu} \int_{0}^{y} (\overline{u}_{l} + w_{0}(\eta)) d\eta\right\}$$

$$= \frac{1}{2} \exp\left\{-\frac{1}{2\nu} \int_{0}^{y} (\overline{u}_{l} + w_{0}(\eta)) d\eta\right\}.$$

Due to (3.84), similar calculations yield

$$(1 - g^{\nu}(y)) \exp\left\{-\frac{1}{2\nu} \int_{0}^{y} u_{0}(\eta) d\eta\right\} = \frac{1}{2} \exp\left\{-\frac{1}{2\nu} \int_{0}^{y} (\overline{u}_{r} + w_{0}(\eta)) d\eta\right\}.$$

Hence, one has that

$$P_{l}(x,t) = \int_{\mathbb{R}} (\overline{u}_{l} + w_{0}(y)) \exp\left\{-\frac{(x-y)^{2}}{4\nu t} - \frac{1}{2\nu} \int_{0}^{y} (\overline{u}_{l} + w_{0}(\eta)) d\eta\right\} dy,$$

$$P_{r}(x,t) = \int_{\mathbb{R}} (\overline{u}_{r} + w_{0}(y)) \exp\left\{-\frac{(x-y)^{2}}{4\nu t} - \frac{1}{2\nu} \int_{0}^{y} (\overline{u}_{r} + w_{0}(\eta)) d\eta\right\} dy,$$

$$Q_{l}(x,t) = \int_{\mathbb{R}} \exp\left\{-\frac{(x-y)^{2}}{4\nu t} - \frac{1}{2\nu} \int_{0}^{y} (\overline{u}_{l} + w_{0}(\eta)) d\eta\right\} dy,$$

$$Q_{r}(x,t) = \int_{\mathbb{R}} \exp\left\{-\frac{(x-y)^{2}}{4\nu t} - \frac{1}{2\nu} \int_{0}^{y} (\overline{u}_{r} + w_{0}(\eta)) d\eta\right\} dy.$$

Moreover, by using the Hopf formula (3.81) for $u_l^{\nu}(x,t)$ and $u_r^{\nu}(x,t)$, respectively, one gets that

$$u_l^{\nu}(x,t) = \frac{P_l(x,t)}{Q_l(x,t)}$$
 and $u_r^{\nu}(x,t) = \frac{P_r(x,t)}{Q_r(x,t)}$. (3.87)

If $t = t_k = \frac{kp}{\overline{u}_l - \overline{u}_r} = \frac{kp}{4\nu\lambda}$, it holds that

$$\begin{split} Q_r(x,t_k) &= \int_{\mathbb{R}} \exp\left\{-\frac{(y-x)^2}{4\nu t_k} + \frac{1}{2\nu} \int_0^y 4\nu\lambda d\eta - \frac{1}{2\nu} \int_0^y \left(\overline{u}_l + w_0(\eta)\right) d\eta\right\} dy \\ &= e^{2\lambda x + 4\lambda^2 \nu t_k} \int_{\mathbb{R}} \exp\left\{-\frac{(y-x-4\lambda\nu t_k)^2}{4\nu t_k} - \frac{1}{2\nu} \int_0^y \left(\overline{u}_l + w_0(\eta)\right) d\eta\right\} dy \\ &= e^{2\lambda x + 4\lambda^2 \nu t_k} \int_{\mathbb{R}} \exp\left\{-\frac{(y-x)^2}{4\nu t_k} - \frac{1}{2\nu} \int_0^{y+4\lambda\nu t_k} \left(\overline{u}_l + w_0(\eta)\right) d\eta\right\} dy \end{split}$$

$$= e^{2\lambda x + 4\lambda^2 \nu t_k - 2\lambda \overline{u}_l t_k} \int_{\mathbb{R}} \exp\left\{-\frac{(y - x)^2}{4\nu t_k} - \frac{1}{2\nu} \int_0^y (\overline{u}_l + w_0(\eta)) d\eta\right\} \times \exp\left\{-\frac{1}{2\nu} \int_y^{y + 4\lambda \nu t_k} w_0(\eta) d\eta\right\} dy.$$

Then due to $\int_0^p w_0(x)dx = 0$ and $4\lambda \nu t_k = kp$, it holds that

$$Q_r(x, t_k) = e^{2\lambda(x - st_k)} Q_l(x, t_k), \qquad x \in \mathbb{R}$$

Similarly, one can get that

$$P_r(x, t_k) = e^{2\lambda(x - st_k)} P_l(x, t_k) - 4\lambda e^{2\lambda(x - st_k)} Q_l(x, t_k), \qquad x \in \mathbb{R}.$$

Hence, (3.86) yields that

$$u^{\nu}(x,t_{k}) = \frac{P_{l}(x,t_{k}) + e^{2\lambda(x-st_{k})}P_{l}(x,t_{k}) - 4\lambda e^{2\lambda(x-st_{k})}Q_{l}(x,t_{k})}{Q_{l}(x,t_{k}) + e^{2\lambda(x-st_{k})}Q_{l}(x,t_{k})}$$

$$= \frac{P_{l}(x,t_{k})}{Q_{l}(x,t_{k})} - 4\lambda\left(1 - g^{\nu}(x-st_{k})\right).$$
(3.88)

Meanwhile, (3.87) yields that

$$u_l^{\nu}(x, t_k) = \frac{P_l(x, t_k)}{Q_l(x, t_k)}$$
 and $u_r^{\nu}(x, t_k) = \frac{P_l(x, t_k) - 4\lambda \ Q_l(x, t_k)}{Q_l(x, t_k)} = \frac{P_l(x, t_k)}{Q_l(x, t_k)} - 4\lambda$,

which, together with (3.88), yields (2.21).

3.4. An example of non-zero shift.

In this section, we prove the result (2) in Theorem 1.3, where the two periodic perturbations are assumed to be the same, $w_{0l} = w_{0r} = w_0$, where $w_0 \in L^{\infty}(\mathbb{R})$ is any periodic function with the period p > 0 and zero average, satisfying $0 < ||w_0||_{L^{\infty}(\mathbb{R})} < (\overline{u}_l - \overline{u}_r)/2$. For any $x \in \mathbb{R}$ and t > 0, it holds that

$$u_l^{\nu}(x,t) \geqslant \inf u_l^{\nu}(\cdot,0) \geqslant \overline{u}_l - \|w_0\|_{L^{\infty}(\mathbb{R})},$$

$$u_r^{\nu}(x,t) \leqslant \sup u_r^{\nu}(\cdot,0) \leqslant \overline{u}_r + \|w_0\|_{L^{\infty}(\mathbb{R})}.$$

Since $\overline{u}_r + \|w_0\|_{L^{\infty}(\mathbb{R})} < \overline{u}_l - \|w_0\|_{L^{\infty}(\mathbb{R})}$, one can construct a smooth and strictly convex function f such that $f(u) = \frac{1}{2n}u^2$ when $u \leq \overline{u}_r + \|w_0\|_{L^{\infty}(\mathbb{R})}$ and $f(u) = \frac{1}{2}u^2$ when $u \geq \overline{u}_l - \|w_0\|_{L^{\infty}(\mathbb{R})}$, where n is a positive number to be determined later; see Figure 2.

Note that $w_l^{\nu} = u_l^{\nu} - \overline{u}_l$ and $w_r^{\nu} = u_r^{\nu} - \overline{u}_r$ have zero average, then one has that

$$\int_{0}^{\infty} \int_{0}^{p} \left(f(u_{l}^{\nu}) - f(\overline{u}_{l}) \right) dx dt = \int_{0}^{\infty} \int_{0}^{p} \frac{(u_{l}^{\nu})^{2} - \overline{u}_{l}^{2}}{2} dx dt = \int_{0}^{\infty} \int_{0}^{p} \frac{(w_{l}^{\nu})^{2}}{2} dx dt, \quad (3.89)$$

$$\int_{0}^{\infty} \int_{0}^{p} \left(f(u_{r}^{\nu}) - f(\overline{u}_{r}) \right) dx dt = \int_{0}^{\infty} \int_{0}^{p} \frac{(u_{l}^{\nu})^{2} - \overline{u}_{r}^{2}}{2n} dx dt = \int_{0}^{\infty} \int_{0}^{p} \frac{(w_{l}^{\nu})^{2}}{2n} dx dt. \quad (3.90)$$

Since w_0 is not identically zero, the solution $u_l^{\nu}(x,t)$ with the initial data $\overline{u}_l + w_0(x)$ cannot be a constant in $\mathbb{R} \times [0, +\infty)$, thus the integral of (3.89) is positive. And more importantly, this integral is independent of n, since no matter what n is, the range of $u_l^{\nu}(x,t)$ is always in the interval where f(u) is $u^2/2$, which means that $u_l^{\nu}(x,t)$ is actually a solution to the Burgers' equation.

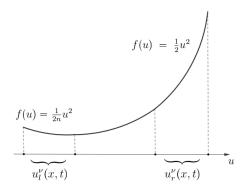


FIGURE 2. Construction of f

On the other side, for the solution $u_r^{\nu}(x,t)$, (A.2) yields that

$$\int_0^{+\infty} \int_0^p (w_r^{\nu})^2 dx dt \leqslant C,$$

where C is independent of f, depending only on ν , p and $||u_r^{\nu}(x,0)||_{L^{\infty}}$. It follows from this and (3.90) that

$$\int_0^\infty \int_0^p \left(f(u_r^{\nu}) - f(\overline{u}_r) \right) dx dt \leqslant \frac{C}{2n}. \tag{3.91}$$

By (3.89) and (3.91), one can choose n sufficiently large such that

$$\int_0^\infty \int_0^p \left(f(u_l^{\nu}) - f(\overline{u}_l) \right) dx dt > \int_0^\infty \int_0^p \left(f(u_r^{\nu}) - f(\overline{u}_r) \right) dx dt,$$

which implies that $X_{\infty,2}^{\nu} \neq 0$. The proof of Theorem 1.3 is finished.

3.5. Vanishing viscosity limit for the shift.

We now study the vanishing viscosity limit for $X_{\infty,2}^{\nu}$ defined in (1.11).

Lemma 3.8. There exists a constant C > 0, independent of either time t or viscosity ν , such that for all $0 \le \nu \le 1$, it holds that

$$\sup_{x \in \mathbb{R}} |u_l^{\nu} - \overline{u}_l| + \sup_{x \in \mathbb{R}} |u_r^{\nu} - \overline{u}_r| \leqslant \frac{C}{1+t}, \quad t \geqslant 0.$$
 (3.92)

Proof. The proof can be found in Xin [30], which relies on the Oleı̆nik's entropy condition (1.4). In fact, for i = l or r, it follows from $\int_0^{p_i} \partial_x u_i^{\nu}(x,t) dx = 0$ and (1.4) that for any $0 < \nu \le 1$ and t > 0,

$$\int_{x \in (0,p_i), \partial_x u_i^{\nu} < 0} \left| \partial_x u_i^{\nu}(x,t) \right| dx = \int_{x \in (0,p_i), \partial_x u_i^{\nu} > 0} \partial_x u_i^{\nu}(x,t) dx \leqslant \frac{p_i E}{1+t},$$

which yields that for any $0 < \nu \le 1$ and t > 0,

$$\sup_{x} |u_i^{\nu} - \overline{u}_l| \leqslant \int_0^{p_i} |\partial_x u_i^{\nu}(x, t)| \, dx \leqslant \frac{2p_i E}{1 + t}.$$

Since u_l^{ν} and u_r^{ν} converges almost everywhere to the periodic entropy solutions u_l^0 and u_r^0 , respectively, (3.92) also holds true for $\nu = 0$.

Proof of Theorem 1.4. For $0 \le \nu \le 1$, it follows from Taylor's expansion and zero average of $u_l^{\nu} - \overline{u}_l$ that

$$\int_{0}^{p_{l}} (f(u_{l}^{\nu}) - f(\overline{u}_{l})) dx = \int_{0}^{p_{l}} \left[f'(\overline{u}_{l})(u_{l}^{\nu} - \overline{u}_{l}) + \frac{1}{2} f''(\cdot)(u_{l}^{\nu} - \overline{u}_{l})^{2} \right] dx$$
$$= \frac{1}{2} \int_{0}^{p} f''(\cdot)(u_{l}^{\nu} - \overline{u}_{l})^{2} dx.$$

This, together with Lemma 3.8 and the strict convexity of f, implies that

$$0 < \int_0^{p_l} \left(f(u_l^{\nu}) - f(\overline{u}_l) \right) dx \le \frac{C}{(1+t)^2}, \tag{3.93}$$

where C is independent of ν or t. Similarly, one has that

$$0 < \int_0^{p_r} \left(f(u_r^{\nu}) - f(\overline{u}_r) \right) dx \le \frac{C}{(1+t)^2}. \tag{3.94}$$

Hence, applying the dominated convergence theorem in (1.11) yields that, one can get that as $\nu \to 0+$,

$$X_{\infty,2}^{\nu} \to \int_{0}^{+\infty} \frac{1}{p_{l}} \int_{0}^{p_{l}} \left(f(u_{l}^{0}) - f(\overline{u}_{l}) \right) dx dt - \frac{1}{p_{l}} \int_{0}^{p_{l}} \int_{0}^{x} w_{0l}(y) dy dx - \int_{0}^{+\infty} \frac{1}{p_{l}} \int_{0}^{p_{r}} \left(f(u_{r}^{0}) - f(\overline{u}_{r}) \right) dx dt + \frac{1}{p_{r}} \int_{0}^{p_{r}} \int_{0}^{x} w_{0r}(y) dy dx.$$

$$(3.95)$$

Now we prove that this limit is equal to

$$X_{\infty,2}^{0} = -\min_{x \in \mathbb{R}} \int_{0}^{x} w_{0l}(y) dy + \min_{x \in \mathbb{R}} \int_{0}^{x} w_{0r}(y) dy.$$

In fact, for i = l or r, since the anti-derivative variable $\int_0^x w_{0i}(y)dy$ is continuous and periodic with the period p_i , one can choose a constant $x_i \in [0, p_i)$ such that

$$\int_0^{x_i} w_{0i}(y)dy = \min_{x \in [0, p_i]} \int_0^x w_{0i}(y)dy, \tag{3.96}$$

which is equivalent to

$$\int_{x_i}^x w_{0i}(y)dy \geqslant 0, \qquad x \in \mathbb{R}.$$

Then one can complete the proof of (1.12) if there holds

$$\int_{0}^{+\infty} \int_{0}^{p_{i}} \left(f(u_{i}^{0}) - f(\overline{u}_{i}) \right) dx dt = \int_{0}^{p_{i}} \int_{x_{i}}^{x} w_{0i}(y) dy dx. \tag{3.97}$$

To prove (3.97), it follows from [2, Theorem 14.1.1] that the periodic entropy solution u_i^0 takes the constant value \overline{u}_i along the straight line $x = x_i + f'(\overline{u}_i)t$. Then for any given $y \in (x_i, x_i + p_i)$ and t > 0, denote the domain

$$\Omega_{(y,t)} := \{ (x,\tau) : x_i + f'(\overline{u}_i)\tau < x < y + f'(\overline{u}_i)\tau, \ 0 < \tau < t \}.$$

Integrating the equation $\partial_t u_i^0 + \partial_x f(u_i^0) = 0$ over $\Omega_{(u,t)}$, one can obtain that

$$0 = -\int_{x_i}^{y} (\overline{u}_i + w_{0i}(x)) dx + \int_{0}^{t} (f(u_i^0) - f'(\overline{u}_i)u_i^0) (y + f'(\overline{u}_i)\tau, \tau) d\tau$$
$$-\int_{0}^{t} (f(\overline{u}_i) - f'(\overline{u}_i)\overline{u}_i) d\tau + \int_{x_i + f'(\overline{u}_i)t}^{y + f'(\overline{u}_i)t} u_i^0(x, t) dx$$

$$= -\int_{x_i}^{y} w_{0i}(x)dx + \int_{0}^{t} \left(f(u_i^0) - f(\overline{u}_i) \right) \left(y + f'(\overline{u}_i)\tau, \tau \right) d\tau$$

$$- f'(\overline{u}_i) \int_{0}^{t} (u_i^0 - \overline{u}_i) \left(y + f'(\overline{u}_i)\tau, \tau \right) d\tau + \int_{x_i + f'(\overline{u}_i)t}^{y + f'(\overline{u}_i)t} \left(u_i^0(x, t) - \overline{u}_i \right) dx.$$

$$(3.98)$$

Then integrating (3.98) with respect to y over $(x_i, x_i + p_i)$ yields that

$$0 = -\int_{x_{i}}^{x_{i}+p_{i}} \int_{x_{i}}^{y} w_{0i}(x) dx dy + \int_{x_{i}}^{x_{i}+p_{i}} \int_{0}^{t} \left(f(u_{i}^{0}) - f(\overline{u}_{i}) \right) (y + f'(\overline{u}_{i})\tau, \tau) d\tau dy$$
$$+ \int_{x_{i}}^{x_{i}+p_{i}} \int_{x_{i}+f'(\overline{u}_{i})t}^{y+f'(\overline{u}_{i})t} \left(u_{i}^{0}(x,t) - \overline{u}_{i} \right) dx dy.$$

Since $\int_{x_i}^y w_{0i}(x)dx$ is periodic with respect to y, and

$$\int_{x_i}^{x_i+p_i} \int_{x_i+f'(\overline{u}_i)t}^{y+f'(\overline{u}_i)t} \left(u_i^0(x,t) - \overline{u}_i \right) dx dy = O\left(\frac{1}{1+t}\right),$$

then it holds that

$$\int_{0}^{t} \int_{0}^{p_{i}} \left(f(u_{i}^{0}(x,\tau)) - f(\overline{u}_{i}) \right) dx d\tau = \int_{0}^{p_{i}} \int_{x_{i}}^{y} w_{0i}(x) dx dy + O\left(\frac{1}{1+t}\right). \tag{3.99}$$

By (3.93) and (3.94), (3.97) follows by letting $t \to +\infty$ and using the dominated convergence theorem in (3.99).

It remains to prove (1.13) to finish the proof of Theorem 1.4. If both the periodic perturbations w_{0l} and w_{0r} have bounded total variations on their respective periodic domains,

$$\text{TV}_{[0,p_l]}(w_{0l}) < +\infty, \quad \text{TV}_{[0,p_r]}(w_{0r}) < +\infty,$$

then it can be derived from the Kruzhkov's theory (see [21, 19]) that, for i = l or r, the viscous solution u_i^{ν} to (1.1) tends to the inviscid entropy solution u_i^0 in the L^1 norm at the following rate,

$$\int_{0}^{p_{i}} \left| u_{i}^{\nu}(x,t) - u_{i}^{0}(x,t) \right| dx \leq C(\nu t)^{1/2} \operatorname{TV}_{[0,p_{i}]}(w_{0i}), \quad t > 0, 0 \leq \nu \leq 1, \quad (3.100)$$

where C > 0 is independent of either ν or t. Then for i = l or r and any given T > 0, one has that

$$\int_{0}^{+\infty} \int_{0}^{p_{i}} \left(f(u_{i}^{\nu}) - f(\overline{u}_{i}) \right) dx d\tau - \int_{0}^{+\infty} \int_{0}^{p_{i}} \left(f(u_{i}^{0}) - f(\overline{u}_{i}) \right) dx d\tau$$

$$= \int_{0}^{T} \int_{0}^{p_{i}} \left(f(u_{i}^{\nu}) - f(u_{i}^{0}) \right) dx d\tau + \int_{T}^{+\infty} \int_{0}^{p_{i}} \left(f(u_{i}^{\nu}) - f(\overline{u}_{i}) \right) dx d\tau$$

$$- \int_{T}^{+\infty} \int_{0}^{p_{i}} \left(f(u_{i}^{0}) - f(\overline{u}_{i}) \right) dx d\tau.$$

It follows from (3.93), (3.94) and (3.100) that

$$\left| \int_0^{+\infty} \int_0^{p_i} \left(f(u_i^{\nu}) - f(\overline{u}_i) \right) dx d\tau - \int_0^{+\infty} \int_0^{p_i} \left(f(u_i^0) - f(\overline{u}_i) \right) dx d\tau \right|$$

$$\leq C \left\{ \nu^{1/2} \int_0^T t^{1/2} dt + \int_T^{+\infty} \frac{1}{(1+t)^2} dt \right\} \leq C \left(\nu^{1/2} T^{3/2} + T^{-1} \right).$$

Letting $T = \nu^{-1/5}$ in the above inequality yields that

$$\left| \int_0^{+\infty} \int_0^{p_i} \left(f(u_i^{\nu}) - f(\overline{u}_i) \right) dx d\tau - \int_0^{+\infty} \int_0^{p_i} \left(f(u_i^0) - f(\overline{u}_i) \right) dx d\tau \right| \leqslant C \nu^{1/5}.$$

It follows from this and the formulas of $X_{\infty,2}^{\nu}$ and $X_{\infty,2}^{0}$ that

$$|X_{\infty,2}^{\nu} - X_{\infty,2}^{0}| \leqslant C\nu^{1/5},$$

where C > 0 is independent of ν .

4. Stability of rarefaction waves

The proof of Theorem 1.5 can follow from the idea in [16]. To make this paper complete, we still give the details here. The proof consists of two steps. The first step is to prove a time-independent estimate of the solution u, just as Proposition 3.4 for the shock profile. Step 2 is to construct an auxiliary function and use the maximal principle to complete the proof.

Proposition 4.1. For any $\varepsilon > 0$, there exist $N_{\varepsilon} > 0$ and $T_{\varepsilon} > 0$ such that

$$|u^{\nu}(x,t) - \overline{u}_l| \le \varepsilon, \qquad t > T_{\varepsilon}, \ x - f'(\overline{u}_l)t < -N_{\varepsilon},$$
 (4.1)

$$|u^{\nu}(x,t) - \overline{u}_r| \le \varepsilon, \qquad t > T_{\varepsilon}, \ x - f'(\overline{u}_r)t > N_{\varepsilon}.$$
 (4.2)

Proof. We prove (4.1) only, since the proof of (4.2) is similar.

For any $\varepsilon > 0$, it follows from Lemma 2.1 that there exists $T_0 > 0$ such that for any $x \in \mathbb{R}, t \geq T_0$, $|u_l^{\nu}(x,t) - \overline{u}_l| < \varepsilon \nu/2$. Since f is strictly convex, there exists $c_0 > 0$ such that, for any $0 < \sigma < 2 ||u_0||_{L^{\infty}(\mathbb{R})}$,

$$f'(\overline{u}_l + \sigma) - f'(\overline{u}_l) > c_0 \sigma.$$

Without loss of generality, one can assume that $\varepsilon > 0$ is small enough such that $c_0 \varepsilon < 2\beta$, where $\beta > 0$ is defined in (2.6). By Lemma 2.3 and $\|u^{\nu}\|_{L^{\infty}(dx,dt)} \leqslant \|u_0\|_{L^{\infty}}$, one can choose M > 0 large enough such that

$$Me^{\frac{c_0\varepsilon}{2}(x-f'(\overline{u}_l)T_0)} + \frac{\varepsilon\nu}{2} + \overline{u}_l > u^{\nu}(x,T_0) \quad \forall x \in \mathbb{R}.$$

Define

$$V(x,t) := Me^{\frac{c_0\varepsilon}{2}(x-f'(\overline{u}_l)t)} + \frac{\varepsilon\nu}{2} + \overline{u}_l - u^{\nu}(x,t).$$

Then $V(x,T_0)>0$ and

$$\nu \partial_x^2 V - \partial_t V - f'(u^{\nu}) \partial_x V = M \frac{c_0 \varepsilon}{2} e^{\frac{c_0 \varepsilon}{2} (x - f'(\overline{u}_l)t)} \left(\frac{c_0 \varepsilon \nu}{2} + f'(\overline{u}_l) - f'(u^{\nu}) \right). \tag{4.3}$$

If the minimum of V over the domain $\{(x,t): x \in \mathbb{R}, t \geq T_0\}$, which is attained at the point (x_0,t_0) , is negative, then by the definition of V, one has that $\overline{u}_l - u^{\nu}(x_0,t_0) < -\frac{\varepsilon\nu}{2}$, and then

$$f'(\overline{u}_l) - f'(u^{\nu}(x_0, t_0)) < f'(\overline{u}_l) - f'(\overline{u}_l + \frac{\varepsilon \nu}{2}) \leqslant -\frac{c_0 \varepsilon \nu}{2}.$$

Thus, (4.3) yields that at the point (x_0, t_0) ,

$$\nu \partial_x^2 V - \partial_t V - f'(u^{\nu}) \partial_x V < 0.$$

Therefore, it follows from the maximum principle that $V(x,t) \ge 0$ for any $x \in \mathbb{R}, t \ge T$. Choosing $N := \frac{2}{c_0 \varepsilon} \ln \frac{\varepsilon}{2M}$, one has that for any $t > T_0$ and $x - f'(\overline{u}_l)t < -N$,

$$u^{\nu}(x,t) \leqslant \overline{u}_l + \frac{\varepsilon\nu}{2} + Me^{\frac{c_0\varepsilon}{2}(x - f'(\overline{u}_l)t)} < \overline{u}_l + \varepsilon. \tag{4.4}$$

On the other hand, for any $\varepsilon > 0$ and the initial data u_0 satisfying (1.3), one can let $\tilde{u}(x,t)$ be the unique solution to (1.1) with the L^{∞} initial data

$$\tilde{u}(x,0) = \begin{cases} u_0(x), & x < 0, \\ \overline{u}_l - \varepsilon/2 + (u_0(x) - \overline{u}_r), & x > 0, \end{cases}$$

which satisfies

$$\begin{cases} |\tilde{u}(x,0) - \overline{u}_l - w_{0l}(x)| \leqslant C_0 e^{\beta_0 x}, \\ |\tilde{u}(x,0) - (\overline{u}_l - \varepsilon/2) - w_{0r}(x)| \leqslant C_0 e^{-\beta_0 x}, \end{cases} \quad x \in \mathbb{R}.$$

Theorem 1.1 implies that as $t \to +\infty$, \tilde{u} tends to a viscous shock profile $\tilde{\phi}$ connecting \overline{u}_l as $x \to -\infty$ and $\overline{u}_l - \varepsilon/2$ as $x \to +\infty$, respectively. Thus, there exists $T_1 > 0$ such that

$$\tilde{u}(x,t) \geqslant \tilde{\phi}(x-st) - \varepsilon/2 \geqslant \overline{u}_l - \varepsilon \qquad \forall x \in \mathbb{R}, t \geqslant T_1.$$
 (4.5)

It follows from $\tilde{u}(x,0) \leq u_0(x)$ and the comparison principle that

$$u^{\nu}(x,t) \geqslant \tilde{u}(x,t) \geqslant \overline{u}_l - \varepsilon \qquad \forall x \in \mathbb{R}, t \geqslant T_1.$$
 (4.6)

Then (4.1) follows from (4.4) and (4.6).

Proof of Theorem 1.5. It is equivalent to prove that for any $\varepsilon > 0$, there exists T > 0 such that

$$\sup_{x \in \mathbb{R}} \left| u^{\nu}(x, t) - u^{R}(x, t) \right| < \varepsilon, \qquad t > T.$$
(4.7)

For the constants N_{ε} and T_{ε} in Proposition 4.1, we define two constants

$$x_0 := N_{\varepsilon} \frac{f'(\overline{u}_l) + f'(\overline{u}_r)}{f'(\overline{u}_l) - f'(\overline{u}_r)} \text{ and } t_0 := \frac{-2N_{\varepsilon}}{f'(\overline{u}_l) - f'(\overline{u}_r)} > 0,$$

and the region

$$\Omega_{\varepsilon} := \{(x, t) : f'(\overline{u}_l)t - N_{\varepsilon} < x < f'(\overline{u}_r)t + N_{\varepsilon}, \ t > T_{\varepsilon} \}.$$

The shifted centered rarefaction wave $\tilde{u}^R(x,t) := u^R(x-x_0,t+t_0)$ satisfies that

$$\tilde{u}^{R}(x,t) = \begin{cases} \overline{u}_{l}, & x - f'(\overline{u}_{l})t \leq -N_{\varepsilon}, \\ (f')^{-1}\left(\frac{x-x_{0}}{t+t_{0}}\right), & x \in \Omega_{\varepsilon}, \\ \overline{u}_{r}, & x - f'(\overline{u}_{r})t \geq N_{\varepsilon}. \end{cases}$$

Therefore, Proposition 4.1 implies that for any $x < f'(\overline{u}_l)t - N_{\varepsilon}$ or $x > f'(\overline{u}_r)t + N_{\varepsilon}$, $t \ge T_{\varepsilon}$,

$$\left| u^{\nu}(x,t) - \tilde{u}^{R}(x,t) \right| < \varepsilon. \tag{4.8}$$

Define

$$Z(x,t) := (t+t_0)^{\kappa} \left(u^{\nu}(x,t) - \tilde{u}^R(x,t) \right), \tag{4.9}$$

where $0 < \kappa < 1$ is a constant to be determined. Direct calculations show that

$$\nu \partial_x^2 Z - f'(u^{\nu}) \partial_x Z - \partial_t Z = \left(f''(v) \partial_x \tilde{u}^R - \frac{\kappa}{t + t_0} \right) Z - \nu (t + t_0)^{\kappa} \partial_x^2 \tilde{u}^R \quad \text{in } \Omega_{\varepsilon}, \tag{4.10}$$

where v is the function satisfying

$$f'(u^{\nu}) - f'(\tilde{u}^R) = f''(v)(u^{\nu} - \tilde{u}^R).$$

For $(x,t) \in \Omega_{\varepsilon}$, it holds that $f''(v)\partial_x \tilde{u}^R = f''(v)\frac{1}{f''(\tilde{u}^R)}\frac{1}{t+t_0} > \frac{2\omega}{t+t_0}$ for some $\omega > 0$. Then $0 < \kappa < 1$ can be chosen small enough such that

$$f''(v)\partial_x \tilde{u}^R - \frac{\kappa}{t + t_0} > \frac{\omega}{t + t_0} > 0. \tag{4.11}$$

Note that for any $x \in \mathbb{R}$,

$$|Z(x,T_{\varepsilon})| \leq M_1(T_{\varepsilon} + t_0)^{\kappa},$$

where the constant $M_1 > \|u_0\|_{L^{\infty}} + \|u^R\|_{L^{\infty}}$ is large enough. Due to (4.8), one has that for any $t \geqslant T_{\varepsilon}$, if $x = f'(\overline{u}_l)t - N_{\varepsilon}$ or $f'(\overline{u}_r)t + N_{\varepsilon}$, $|Z(x,t)| \leqslant \varepsilon(t+t_0)^{\kappa}$.

If the maximum of Z over the domain Ω_{ε} is attained at (x_1, t_1) and satisfies that

$$Z(x_1, t_1) \geqslant \max\left\{M_1(T_{\varepsilon} + t_0)^{\kappa}, \varepsilon(t_1 + t_0)^{\kappa}, \frac{M_1}{\omega}(T_{\varepsilon} + t_0)^{\kappa - 1}\right\} > 0. \tag{4.12}$$

Then by (4.10)–(4.12), one has that at $(x_1, t_1) \in \Omega_{\varepsilon}$,

$$\nu \partial_x^2 Z - f'(u^{\nu}) \partial_x Z - \partial_t Z \geqslant \frac{\omega}{t_1 + t_0} \frac{M_1}{\omega} (T_{\varepsilon} + t_0)^{\kappa - 1} - \nu (t_1 + t_0)^{\kappa} \frac{M_2}{(t_1 + t_0)^2} > 0,$$

where $M_5 = \max |((f')^{-1})''|$ and then let $M_1 > M_2$ be large enough. Therefore, the maximal principle implies that for any $(x,t) \in \Omega_{\varepsilon}$,

$$Z(x,t) \leq \max \Big\{ M_1(T_{\varepsilon} + t_0)^{\kappa}, \varepsilon(t + t_0)^{\kappa}, \frac{M_1}{\omega} (T_{\varepsilon} + t_0)^{\kappa - 1} \Big\}.$$

Similarly, one can verify that for any $(x,t) \in \Omega_{\varepsilon}$.

$$Z(x,t) \geqslant \min \left\{ -M_1(T_{\varepsilon} + t_0)^{\kappa}, -\varepsilon(t + t_0)^{\kappa}, -\frac{M_1}{\omega}(T_{\varepsilon} + t_0)^{\kappa - 1} \right\}.$$

As a result, by choosing a large $T > T_{\varepsilon}$, one can get that

$$\left| u^{\nu}(x,t) - u^{R}(x - x_{0}, t + t_{0}) \right| \leq \max \left\{ \frac{M_{1}(T_{\varepsilon} + t_{0})^{\kappa}}{(t + t_{0})^{\kappa}}, \varepsilon, \frac{M_{1}}{(T_{\varepsilon} + t_{0})^{1 - \kappa}(t + t_{0})^{\kappa}} \right\}$$

$$\leq \varepsilon \quad \forall t > T, f'(\overline{u}_{l})t - N_{\varepsilon} < x < f'(\overline{u}_{r})t + N_{\varepsilon}.$$
(4.1)

Moreover, since u^R is Lipschitz continuous and $\frac{x}{t} - \frac{x - x_0}{t + t_0} \to 0$ as $t \to +\infty$, (4.7) follows easily from combining Proposition 4.1 and (4.13), and thus Theorem 1.5 is proved.

Appendix A. Proof of Lemma 2.1

Proof. For convenience, we let $\nu = 1$ and omit the symbol ν . By multiplying $u - \overline{u}$ on each side of (1.1) and integrating on [0, p], it holds that

$$\frac{d}{dt} \int_0^p (u - \overline{u})^2(x, t) dx + 2 \int_0^p (\partial_x u)^2(x, t) dx = 0, \qquad t > 0.$$
 (A.1)

By the Poincaré inequality on [0, p], there exists a constant $\alpha > 0$, which depends only on p, such that

$$\int_0^p (\partial_x u)^2(x,t)dx \geqslant \frac{\alpha}{2} \int_0^p (u - \overline{u})^2(x,t)dx.$$

Then by (A.1), one has

$$\int_{0}^{p} (u - \overline{u})^{2}(x, t) dx \leqslant C_{0} e^{-\alpha t} \quad \forall t \geqslant 0, \tag{A.2}$$

where $C_0 = \int_0^p (u_0 - \overline{u})^2 dx$ depends on p and $||u_0||_{L^{\infty}}$.

Claim 1. For any integer $k \ge 1$,

$$\int_0^p (\partial_x^k u)^2(x,t) dx \leqslant C \quad \forall t \geqslant 1,$$

where C depends on k, p, f and $||u_0||_{L^{\infty}}$.

In fact, for each $k \ge 0$, we let $t_k := \frac{1}{2} - \frac{1}{k+3}$, and define smooth functions $\zeta_k(t) : [0, +\infty) \to [0, 1]$, which are non-decreasing and satisfy that for all $t \ge 0$,

$$\zeta_k(t) = \begin{cases} 0, & t \in [0, t_k] \\ 1, & t \in [1, +\infty) \end{cases} \quad \text{and} \quad \zeta'_k(t) + \zeta_k(t) \leqslant B_k \zeta_{k-1}(t),$$

where $B_k > 0$ is a constant depending on k; see Figure 3.

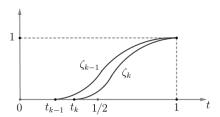


FIGURE 3

Then we prove Claim 1 by the induction method. We will prove that for each $k \ge 1$, there exists a constant C > 0, depending on k, p, f and $||u_0||_{L^{\infty}}$, such that

$$\int_0^p \left(\partial_x^{k-1}(u-\overline{u})\right)^2 dx + \int_0^t \zeta_{k-1}(\tau) \int_0^p (\partial_x^k u)^2 dx d\tau \leqslant C \quad \forall t > t_k.$$
 (A.3)

In fact, when k=1, (A.3) follows from (A.1). Then we assume that (A.3) holds for $k=1,2,\cdots,m$ with $m \geq 1$, and then we will prove that (A.3) also holds for k=m+1. By taking the derivative ∂_x^m in (1.1) and multiplying $\zeta_m \partial_x^m u$ on each side, one can obtain

$$\partial_t (\zeta_m (\partial_x^m u)^2) - \zeta_m' (\partial_x^m u)^2 + \partial_x (\zeta_m \partial_x^m u \partial_x^m f(u)) - \zeta_m \partial_x^{m+1} u \partial_x^m f(u)$$

$$= \partial_x (\zeta_m \partial_x^m u \partial_x^{m+1} u) - \zeta_m (\partial_x^{m+1} u)^2.$$

This, with the Cauchy-Schwartz inequality, yields that for all t > 0,

$$\frac{d}{dt} \int_{0}^{p} \zeta_{m}(t) (\partial_{x}^{m} u)^{2} dx + \zeta_{m}(t) \int_{0}^{p} (\partial_{x}^{m+1} u)^{2} dx$$

$$\leq C(\zeta'_{m} + \zeta_{m}) \sum_{k=1}^{m} \int_{0}^{p} (\partial_{x}^{k} u)^{2} dx$$

$$\leq CB_{m} \zeta_{m-1}(t) \sum_{k=1}^{m} \int_{0}^{p} (\partial_{x}^{k} u)^{2} dx.$$
(A.4)

Thus one can have that for all t > 0,

$$\int_{0}^{p} \zeta_{m}(t) (\partial_{x}^{m} u)^{2} dx + \int_{0}^{t} \zeta_{m}(\tau) \int_{0}^{p} (\partial_{x}^{m+1} u)^{2} dx d\tau$$

$$\leq C_{m} \sum_{k=1}^{m} \int_{0}^{t} \zeta_{k-1}(\tau) \int_{0}^{p} (\partial_{x}^{k} u)^{2} dx d\tau, \tag{A.5}$$

where $C_m > 0$ depends on f, p and $||u_0||_{L^{\infty}}$. Then by (A.3) for $k = 1, 2, \dots, m$, for any $t > t_m$, the right hand side of (A.5) is bounded by a constant, so (A.3) holds true for k = m + 1. Thus, by the induction method, (A.3) holds true for any $k \ge 1$ and any $t \ge 1$, which completes the proof of Claim 1.

Then it follows from Sobolev inequality, Claim 1, and the equation (1.1) that for any integers $k, l \ge 0$,

$$\|\partial_t^l \partial_x^k (u - \overline{u})\|_{L^{\infty}(\mathbb{R})} \leqslant C_{kl} \quad \forall \ t \geqslant 1.$$

And since for each $k \ge 0$, $\zeta_k(t) = 1$ and $\zeta'_k(t) = 0$ for all $t \ge 1$, (A.1) and (A.4) yield that

$$\frac{d}{dt} \int_0^p \left(\partial_x^k (u - \overline{u})\right)^2 dx + \int_0^p (\partial_x^{k+1} u)^2 dx \leqslant C \sum_{l=1}^k \int_0^p (\partial_x^l u)^2 dx \quad \forall t \geqslant 1, \tag{A.6}$$

where C > 0 depends on k, p, f and $||u_0||_{L^{\infty}}$.

Claim 2. For each $k \ge 0$, there holds that

$$\int_{0}^{p} \left(\partial_{x}^{k} (u - \overline{u}) \right)^{2} (x, t) dx \leqslant C e^{-\alpha t} \quad \forall t \geqslant 1, \tag{A.7}$$

where C > 0 depends on k, p, f and $||u_0||_{L^{\infty}}$.

To prove Claim 2, we also use the induction method. For k=0, (A.7) follows from (A.2). Thus, one can assume that for $k=0,1,\cdots,m-1$ with $m \ge 1$, Claim 2 is true. Then for k=m, by (A.6) with k=m, one has that for all $t \ge 1$,

$$\frac{d}{dt} \int_0^p (\partial_x^m u)^2 dx \leqslant C_m \sum_{k=1}^m \int_0^p (\partial_x^k u)^2 dx
\leqslant C e^{-\alpha t} + C_m \int_0^p (\partial_x^m u)^2 dx,$$
(A.8)

where $C, C_m > 0$ depend on m, p, f and $||u_0||_{L^{\infty}}$, and C_m can be large enough such that $C_m > \alpha$. Letting k = m - 1 in (A.6), one gets that for all $t \ge 1$,

$$\frac{d}{dt} \int_0^p \left(\partial_x^{m-1} (u - \overline{u})\right)^2 dx + \int_0^p (\partial_x^m u)^2 dx \leqslant Ce^{-\alpha t}. \tag{A.9}$$

Then by multiplying $2C_m$ on (A.9) and then adding it to (A.8), one can obtain that for all $t \ge 1$,

$$\frac{d}{dt} \left[2C_m \int_0^p \left(\partial_x^{m-1} (u - \overline{u}) \right)^2 dx + \int_0^p (\partial_x^m u)^2 dx \right] + C_m \int_0^p (\partial_x^m u)^2 dx \leqslant Ce^{-\alpha t}. \quad (A.10)$$

Denote

$$E_m(t) := 2C_m \int_0^p \left(\partial_x^{m-1}(u - \overline{u})\right)^2 dx + \int_0^p (\partial_x^m u)^2 dx.$$

Then (A.7) with k = m - 1 and (A.10) yield that for all $t \ge 1$,

$$E'_m(t) + C_m E_m(t) \leqslant C'_m e^{-\alpha t}. \tag{A.11}$$

Since $C_m > \alpha$, one can easily obtain that $E_m(t) \leq Ce^{-\alpha t}$, where C > 0 depends on depends on m, p, f and $||u_0||_{L^{\infty}}$. The proof of $Claim\ 2$ is finished.

Then by Sobolev inequality and Claim 2, and combined with the equation (1.1), one can have that for any integers $k, l \ge 0$ and $t \ge 1$,

$$\|\partial_t^l \partial_x^k (u - \overline{u})\|_{L^{\infty}(\mathbb{R})} \le Ce^{-\alpha t}$$

which finishes the proof of Lemma 2.1.

APPENDIX B. PROOF OF LEMMA 2.2

Proof. For convenience, we assume that $\nu = 1$ and omit the symbol ν . And let $K^t(x) := \frac{1}{\sqrt{2\pi t}} e^{-\frac{x^2}{4t}}$ denote the heat kernel.

As in [5], the solution $S_t u_0$ can be obtained by constructing the following approximating sequence

$$u^{(1)} = K^{t} * u_{0},$$

$$u^{(n+1)} = K^{t} * u_{0} - \int_{0}^{t} \partial_{x} K^{\tau}(\cdot) * f(u^{(n)}(\cdot, t - \tau)) d\tau, \qquad n = 1, 2, \dots.$$

Suppose that $\{\tilde{u}^{(n)}\}_{n=1}^{\infty}$ is the approximating sequence induced by \tilde{u}_0 , constructed in the same way as $u^{(n)}$. Therefore, one has that

$$\begin{aligned} \left| u^{(1)} - \tilde{u}^{(1)} \right| &= \left| K^t * (u_0 - v_0) \right| \leqslant \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi t}} e^{-\frac{y^2}{4t}} C e^{\delta(x - y)} dy \\ &\leqslant \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi t}} e^{-\frac{1}{4t} (y + 2\delta t)^2} C e^{\delta x + \delta^2 t} dy = C e^{\delta x + \delta^2 t}, \\ \left| u^{(2)} - \tilde{u}^{(2)} \right| &\leqslant \left| K^t * (u_0 - \tilde{u}_0) \right| \\ &+ \left| \int_0^t \partial_x K^\tau(\cdot) * \left[f \left(u^{(1)}(\cdot, t - \tau) \right) - f \left(\tilde{u}^{(1)}(\cdot, t - \tau) \right) \right] d\tau \right| \\ &\leqslant C e^{\delta x + \delta^2 t} + \int_0^t \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi \tau}} \frac{|y|}{2\tau} e^{-\frac{y^2}{4\tau}} C_0 C e^{\delta(x - y) + \delta^2(t - \tau)} dy d\tau \\ &\leqslant C e^{\delta x + \delta^2 t} + C_0 C e^{\delta x + \delta^2 t} \int_0^t \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi \tau}} \frac{|y|}{2\tau} e^{-\frac{(y + 2\delta\tau)^2}{4\tau}} dy d\tau \\ &\leqslant C e^{\delta x + \delta^2 t} + C_0 C e^{\delta x + \delta^2 t} \int_0^t \int_{\mathbb{R}} \frac{1}{\sqrt{2\pi \tau}} \left(\frac{|y|}{2\tau} + |\delta| \right) e^{-\frac{y^2}{4\tau}} dy d\tau \end{aligned}$$

$$= Ce^{\delta x + \delta^2 t} + C_0 Ce^{\delta x + \delta^2 t} \int_0^t \left(\sqrt{\frac{2}{\pi \tau}} + |\delta| \right) d\tau$$

$$\leq Ce^{\delta x + \delta^2 t} \left(1 + \frac{2\sqrt{2}}{\sqrt{\pi}} C_0 \sqrt{t} + C_0 |\delta| t \right),$$

where $C_0 := \max \left\{ |f'(u)| : |u| \leqslant ||u_0, \tilde{u}_0||_{L^{\infty}(\mathbb{R})} \right\}$. By induction, one has that for t > 0 small,

$$\left| u^{(n)} - \tilde{u}^{(n)} \right| \leq C e^{\delta x + \delta^2 t} \left[1 + \left(\frac{2\sqrt{2}}{\sqrt{\pi}} C_0 \sqrt{t} + C_0 |\delta| t \right) + \dots + \left(\frac{2\sqrt{2}}{\sqrt{\pi}} C_0 \sqrt{t} + C_0 |\delta| t \right)^{n-1} \right] \\
\leq \frac{C e^{\delta x + \delta^2 t}}{1 - \left(\frac{2\sqrt{2}}{\sqrt{\pi}} C_0 \sqrt{t} + C_0 |\delta| t \right)}.$$

Therefore, by letting $n \to +\infty$, there exists a small enough $t_0 = t_0(|\delta|, C_0)$ with

$$\frac{e^{\delta^2 t_0}}{1 - \left(\frac{2\sqrt{2}}{\sqrt{\pi}}C_0\sqrt{t_0} + C_0|\delta|t_0\right)} < 2,$$

such that $|S_t u_0 - S_t \tilde{u}_0| \leq 2Ce^{\delta x}$ holds for any $x \in \mathbb{R}, t \in (0, t_0]$. At time $t = kt_0$, $k = 1, 2, 3, \ldots$, one can take $S_{kt_0} u_0, S_{kt_0} \tilde{u}_0$ instead of u_0, \tilde{u}_0 as the initial data and then repeat the same estimates as above in the interval $[kt_0, (k+1)t_0]$. It concludes that for any $x \in \mathbb{R}, t > 0$, $|S_t u_0 - S_t \tilde{u}_0| \leq 2^{\frac{t}{t_0}+1} Ce^{\delta x}$.

Appendix C. Proof of Lemma 2.4

Proof. For convenience, we let $\nu = 1$ and omit the symbol ν . Integrating the equation (1.5) shows that the shock profile ϕ satisfies

$$\phi' = f(\phi) - f(\overline{u}_l) - s(\phi - \overline{u}_l),$$

which implies that

$$\phi' = (\phi - \overline{u}_l) \left(\frac{f(\phi) - f(\overline{u}_l)}{\phi - \overline{u}_l} - s \right) = (\phi - \overline{u}_r) \left(\frac{f(\phi) - f(\overline{u}_r)}{\phi - \overline{u}_r} - s \right).$$

thus one has that the function $g^{\nu}(x)$ defined in (2.3) satisfies the equation:

$$g' = \frac{1}{\overline{u}_l - \overline{u}_r} \Big[f \Big((\overline{u}_l - \overline{u}_r) g + \overline{u}_r \Big) - f(\overline{u}_r) \Big] - sg$$

$$= \frac{1}{\overline{u}_l - \overline{u}_r} \Big[f \Big(\overline{u}_l g + \overline{u}_r (1 - g) \Big) - f(\overline{u}_l) g - f(\overline{u}_r) (1 - g) \Big].$$
(C.1)

(i) Since f is smooth, for any $x > y, 0 \le \rho \le 1, z = \rho x + (1 - \rho)y$, one has $f(z) - [\rho f(x) + (1 - \rho)f(y)]$ $= \rho(z - x) \int_0^1 f'(\tau z + (1 - \tau)x) d\tau + (1 - \rho)(z - y) \int_0^1 f'(\tau z + (1 - \tau)y) d\tau$ $= \rho(1 - \rho)(x - y) \int_0^1 \int_0^1 (y - x)(1 - \tau) \times$

$$f''(\tilde{\tau}[\tau z + (1-\tau)y] + (1-\tilde{\tau})[\tau z + (1-\tau)x]) d\tilde{\tau}d\tau.$$

Therefore,

$$\frac{1}{2} \min_{u \in [y,x]} f''(u) \leqslant -\frac{f(z) - [\rho f(x) + (1-\rho)f(y)]}{\rho (1-\rho)(x-y)^2} \leqslant \frac{1}{2} \max_{u \in [y,x]} f''(u).$$

Then (2.4) follows by substituting $x = \overline{u}_l, y = \overline{u}_r, \rho = g$ and $z = \overline{u}_l g + \overline{u}_r (1 - g)$, and applying the definition (C.1).

(ii) Integrating the equation (2.4) yields

$$\beta_1 x \leqslant \ln \frac{1 - g(x)}{g(x)} - \beta_3 \leqslant \beta_2 x, \quad x > 0,$$

$$\beta_2 x \leqslant \ln \frac{1 - g(x)}{g(x)} - \beta_3 \leqslant \beta_1 x, \quad x < 0,$$

where $\beta_3 = \ln \frac{1-g(0)}{g(0)}$. And then

$$\begin{split} \frac{1}{1+e^{\beta_2 x+\beta_3}} &\leqslant g(x) \leqslant \frac{1}{1+e^{\beta_1 x+\beta_3}}, \quad x>0, \\ \frac{e^{\beta_2 x+\beta_3}}{1+e^{\beta_2 x+\beta_3}} &\leqslant 1-g(x) \leqslant \frac{e^{\beta_1 x+\beta_3}}{1+e^{\beta_1 x+\beta_3}}, \quad x<0. \end{split}$$

Therefore, (2.5) follows, and C depends on β_1, β_2 and β_3 .

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